

INDIVIDUALS AND POSSIBILITIES (3): Notes on issues raised by Stone & Hardt (1997)

Maria Bittner
Rutgers & IMS

- **Two levels of prominence:** For every type, need two tiers of discourse referents, *central* vs. *peripheral*.
 - **Two levels of abstractness:** The concepts stored as discourse referents can be either *static* or *dynamic*

2. DYNAMIC PROMINENCE HIERARCHY OF REFERENTS IN DISCOURSE

- (1) [a] Yesterday, Juuna^{u1*} went hunting^{e1} by boat^{u5} together with Kaali^{u2} and [his_{*, u2} son]^{u3}.
[b] It_{e1} was great fun. [c] He_{*} steered the boat_{u5} all alone. [d] Suddenly the waves got high.
[e] But Kaali_{u2} had confidence in him_{*}, so he_{*, u2, ?u3} stayed calm.
[e'] But he_{*} had confidence in Kaali_{u2}, so he_{*, u2, ?u3} stayed calm.
[e''] But [his_{*} friend]_{u3} had confidence in Kaali_{u2}, so he_{*, u2, u3} stayed calm.

- (*) In *Eskimo*, dref's are introduced as **central** or *peripheral*, and then promoted or demoted, by case and AGR:

- Intransitive array: NOM_n (OBL) V-MOOD-AGR_n
 [by default] [*peripheral*]
 - Transitive array: ERG_m NOM_n (OBL) $\text{V-MOOD-AGR}_m\text{-AGR}_n$
 [by default] [**central**] [*peripheral*]
 - Two forms of AGR: **i**-form for **central** dref (= current center or just promoted)
 a/u-form for *peripheral* dref (= current periphery or just demoted)

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| (1') [a] Ippasaq Juuna-p | Kaali ^{u2} | irnir-a=lu |
| yesterday Juuna-ERG ^{u1*} | [Kaali] ^{u2} | [son-3SG _{u2}] ^{u3} =and ^{u4} |
| [r: u ₁ , u ₀] u ₁ = <i>juuna</i> , u ₀ = u ₁]; [r: u ₂ = <i>kaali</i>]; [r: u ₃] son-of _r {u ₃ , u ₂ }; [r: u ₄] u ₄ = u ₂ + u ₃ ; | | |

- (²) umiatsia-mik (¹) angala-qatig-a-i
 [VP boat^{*e*₅}-INS_{*e*₁} go.hunting^{*e*₁}-together.with-FCT_{*r*}-3SG.*.3PL_{*u*₄}]
 (¹)[*r*: *e*₁] *go-hunting-together*_{*r*}{*e*₁, *u*₀, *u*₄}]; (²)[*r*: *u*₅] *boat*_{*r*}{*u*₅}, *means*_{*r*}{*u*₅, *e*₁}]

- [b] _ nuanni-qa-u-q.
pro_{e1} be.fun-very.much-FCT_r-3SG_{e1}

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|----------|-----------------------------|--|--|
| [c] _ | umiatsiaq | ⁽²⁾ namminiq | ⁽¹⁾ aqqutirala-pa-a |
| pro-ERG* | boat _{u5} | [_{VP} alone _* , _{e2} steer ^{o2} -FCT-3SG*,3SG _{u5}] | |
| | [boat _{u5}]; | ⁽¹⁾ [r: e ₂] steer _r {e ₂ , u ₀ , u ₅ }]; | ⁽²⁾ [alone _r {u ₀ , e ₂ }] |

- [d] Tassanngaannaq malillir-pu-q.
 suddenly waves.get.high-FCT-3SG

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| [e] Kaali-p=li | - | tatigi-mm- <i>a-ni</i> , | - | iqqissisima-vu-q. |
| Kaali-ERG _{u2} =but | pro* | trust-CAUS ^{p1, p0*} -3SG _{u2} .3SG* | pro* | stay.calm-FCT*-3SG* |
| [u ₂ =kaali]; | | [r: p ₁ , p ₀] because _r (p ₁ , p ₀), trust _{p1} {u ₂ , u ₀ }]; [stay-calm _{p0} {u ₀ }] | | |

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|--|---------------------------------------|--|---|---------------------|
| Kaali-p=li | - | tatigi-ga- mi-uk , | - | iqqissisima-vu-q. |
| Kaali-ERG _{u2*} =but | pro _{u1} | trust-CAUS ^{p1, p0*} -3SG..3SG _{u1} | pro* | stay.calm-FCT*-3SG* |
| [r: u ₀] <u>u₂ = kaali</u> , u ₀ = u ₁]; | [r: p ₁ , p ₀] | because,(p ₁ , p ₀), trust _{p1} {u ₀ , u ₁ }]; | [stay-calm _{p0} {u ₀ }] | |

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|---|---------------------------|--|--------------------------------------|
| [e'] _ | Kaali=li | tatigi-mm- <i>a-ni</i> , | _ iqqissisima-vu-q. |
| pro _{u1} | Kaali _{u2*} =but | trust-CAUS ^{p1, p0*} -3SG _{u1} .3SG _* | pro _* stay.calm-FCT*-3SG* |
| [r: u ₀ <u>u₂</u> = <i>kaali</i> , u ₀ = u ₁]; [r: p ₁ , p ₀] because _r (p ₁ , p ₀), trust _{p1} {u ₁ , u ₀ }]; [l stay-calm _{p0} {u ₀ }] | | | |

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| _ Kaali=li | tatigi-ga- mi-uk , | _ iqqissisima-vu-q. |
| pro* Kaali _{u2} =but | trust-CAUS ^{p1, p0*} -3SG*.3SG _{u2} | pro* stay.calm-FCT*-3SG* |
| [<u>u2</u> =kaali]; | [r: p1, p0] because,(p1, p0), trust _{p1} {u ₀ , u ₂ }]; [stay-calm _{p0} {u ₀ }] | |

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|---|---|---|---|
| [e"] ikinngum- mi =li | Kaali | tatigi-mm- <i>a-gu</i> , | - iqqisisima-vu-q. |
| [friend-3SG*.ERG] _{u3} =but | Kaali _{u2} | trust-CAUS ^{p1, p0*} -3SG _{u3} .3SG _{u2} | pro* stay.calm-FCT*-3SG* |
| [<i>friend</i> _r {u ₃ , u ₀ }]; | [<u>₂</u> = <i>kaali</i>]; | [r: p ₁ , p ₀] because _r (p ₁ , p ₀), trust _{p1} {u ₃ , u ₂ }]; | [stay-calm _{p0} {u ₀ }] |

2. ‘SLOPPY IDENTITY’ = ANAPHORA TO DYNAMIC REFERENT + CENTER SHIFT

- (2) $C1^* \dots [x_p \dots [y_p \dots \dots] \dots]^{\delta} \dots C2^* \dots [x_p \dots]_{\delta}$
- (3) $John^* \text{ spent } [his^* \text{ paycheck}]^{\xi^1}. Bill^* \text{ saved } [it]_{\xi^1}.$ [NP [NP*]]
- (4) $John^* \text{ would use slides } [if he^* \text{ gave a talk}]^{\omega^1}. Bill^* [would]_{\omega^1} \text{ just use the chalkboard.}$ [MOD [NP*]]
- (5) $if a dog bites you^*, I \text{ might } [_ \text{ shoot it}]^{\omega^1}.$ But $if a child bites you^* I wo[n't]_{\omega^1}.$ [MOD [MOD*]]
- (6) $Suppose John left^*.$ Then I’d bet \$5 on [the prediction that Sue **would*** have a breakdown] $^{\xi^1}.$ But $if John stayed,$ then I’d bet \$100 on [this] $_{\xi^1}.$ [NP [MOD*]]

[Note: The formalization in Stone & Hardt 1997 seems unnecessarily complex. What follows is an attempt to simplify their formalism while preserving the intuitive idea of their explanation, and their empirical results.]

$$(3') \quad \begin{matrix} John^{u^1*} \\ (1) [r: u_1, \xi_0] u_1 = john, \xi_0 = u_1]; (2) [r: \xi_1] \xi_1 = paycheck_r\{\xi_0\}; (2?) [\ spend_r\{\xi_0, \xi_1\}] \end{matrix} \quad [VP \text{ spent } [his^* \text{ paycheck}]^{\xi^1}].$$

	i	j_1	j_2
r	$\lambda w \in K.K$	\rightarrow	\rightarrow
u_1	?	$\lambda w.john$	\rightarrow
u_2	?	?	?
ξ_0	?	$\lambda hw.john$	\rightarrow
ξ_1	?	?	$\lambda hw.paycheck_w(\xi_0 hw)$

(2?) tests whether j_2 satisfies:

$$\begin{aligned} & \forall w' (\exists w (w' \in r^o j_2 w) \rightarrow spend_w(\xi_0 j_2 w', \xi_1 j_2 w')) \\ = & \forall w' (w' \in K \rightarrow spend_{w'}(\xi_0 j_2 w', paycheck_w(\xi_0 j_2 w'))) \\ = & \forall w' (w' \in K \rightarrow spend_{w'}(john, paycheck_w(john))) \end{aligned}$$

$$(3) \quad \begin{matrix} Bill^{u^2*} \\ [r: u_2, \xi_0] u_2 = bill, \xi_0 = u_2]; (3?) [\ save_r\{\xi_0, \xi_1\}] \end{matrix} \quad [VP \text{ saved } it_{\xi^1}].$$

	j_2	j_3
r	$\lambda w \in K.K$	\rightarrow
u_1	$\lambda w.john$	\rightarrow
u_2	?	$\lambda w.bill$
ξ_0	$\lambda hw.john$	$\lambda hw.bill$
ξ_1	$\lambda hw.paycheck_w(\xi_0 hw)$	\rightarrow

(3?) tests whether j_3 satisfies:

$$\begin{aligned} & \forall w' (\exists w (w' \in r^o j_3 w) \rightarrow save_{w'}(\xi_0 j_3 w', \xi_1 j_3 w')) \\ = & \forall w' (w' \in K \rightarrow spend_{w'}(\xi_0 j_3 w', paycheck_w(\xi_0 j_3 w'))) \\ = & \forall w' (w' \in K \rightarrow spend_{w'}(bill, paycheck_w(bill))) \end{aligned}$$

(4') John ^{ω_1^{1*}} [VP would _{ω_1} use slides [if he_{*} gave a talk] ^{ω_1}].
⁽¹⁾ [r: $u_1, \xi_0 \vdash u_1 = john, \xi_0 \equiv u_1$]; ⁽²⁾ if(r, ω_1 , [$\vdash give-talk_{\omega_1}(\xi_0)$]); ^(2?) [$\vdash use-slides_{\omega_1}(\xi_0)$]

	<i>i</i>	<i>j</i> ₁	<i>j</i> ₂
<i>r</i>	$\lambda w \in K.K$	\rightarrow	\rightarrow
u_1	?	$\lambda w.john$	\rightarrow
u_2	?	?	?
ξ_0	?	$\lambda hw.john$	\rightarrow
ω_1	?	?	$\lambda h \lambda w \in K. \min_w (\lambda w''. give-talk_w(\xi_0 hw''))$

^(2?) tests whether *j*₂ satisfies:

$$\begin{aligned} & \forall w' (\exists w (w' \in \omega_1 j_2 w) \rightarrow use-slides_w(\xi_0 j_2 w')) \\ = & \forall w (w \in K \rightarrow \forall w' (w' \in \min_w (\lambda w''. give-talk_w(\xi_0 j_2 w'')) \rightarrow use-slides_w(\xi_0 j_2 w'))) \\ = & \forall w (w \in K \rightarrow \forall w' (w' \in \min_w (\lambda w''. give-talk_w(john)) \rightarrow use-slides_w(john))) \end{aligned}$$

Bill ^{ω_2^{1*}} [VP would _{ω_1} use the chalkboard].
⁽³⁾ [r: $u_2, \xi_0 \vdash u_2 = bill, \xi_0 \equiv u_2$]; ^(3?) [$\vdash use-chalkboard_{\omega_1}(\xi_0)$]

	<i>j</i> ₂	<i>j</i> ₃
<i>r</i>	$\lambda w \in K.K$	\rightarrow
u_1	$\lambda w.john$	\rightarrow
u_2	?	$\lambda w.bill$
ξ_0	$\lambda hw.john$	$\lambda hw.bill$
ξ_1	$\lambda h \lambda w \in K. \min_w (\lambda w''. give-talk_w(\xi_0 hw''))$	\rightarrow

^(3?) tests whether *j*₃ satisfies:

$$\begin{aligned} & \forall w' (\exists w (w' \in \omega_1 j_3 w) \rightarrow use-slides_w(\xi_0 j_3 w')) \\ = & \forall w (w \in K \rightarrow \forall w' (w' \in \min_w (\lambda w''. give-talk_w(\xi_0 j_3 w'')) \rightarrow use-chalkboard_w(\xi_0 j_3 w'))) \\ = & \forall w (w \in K \rightarrow \forall w' (w' \in \min_w (\lambda w''. give-talk_w(bill)) \rightarrow use-chalkboard_w(bill))) \end{aligned}$$

- (5') [If a dog^{u1*} bites you]^{p1*}
- ⁽¹⁾ **if**($r, p_1, [p_1: u_1 | \text{dog}_{p_1}\{u_1\}, \text{bite}_{p_1}\{u_1, \text{you}\}]$); ⁽²⁾ [$r: \xi_0, \omega_0 | \xi_0 \equiv u_1, \omega_0 = p_1$];
 I might _{ω_0, ω_1} [_ shoot it _{ξ_0}] _{ω_0} ^{ω_1}
- ⁽³⁾ **if**($\omega_0, \omega_1, [\text{ } | \text{shoot}_{\omega_1}\{me, \xi_0\}]$); ^(3?) [_ **poss** _{ω_0, ω_1}]

Assuming (5) is said by John to Bill:

	i	j_1	j_2	j_3
me	$\lambda w.john$	\rightarrow	\rightarrow	\rightarrow
you	$\lambda w.bill$	\rightarrow	\rightarrow	\rightarrow
r	$\lambda w \in K.K$	\rightarrow	\rightarrow	\rightarrow
u_1	?	$\lambda w.u_1 j_1 w = \lambda w.\mathbf{d}_1 w$ s.t. ($\text{dog}_{p_1}\{u_1\}, \text{bite}_{p_1}\{u_1, \text{you}\}$) j_1	\rightarrow	\rightarrow
u_2	?	?	?	?
p_1	?	$\lambda w \in K.\min_{j_1, w} \mathbf{DB}$	\rightarrow	\rightarrow
p_2	?	?	?	?
ξ_0	?	?	$\lambda h \lambda w.\mathbf{d}_1 w$	\rightarrow
ω_0	?	?	$\lambda h \lambda w \in K.\min_{j_1, w} \mathbf{DB}$	\rightarrow
ω_1	?	?	?	$\lambda h \lambda w' \in \cup_w \omega_0 h w.$ $\min_{h, w'} \text{shoot}\{me, \xi_0\}$

^(3?) tests whether j_3 satisfies the test for **poss** _{ω_0, ω_1} , whether $\omega_0 j_3$ is }, --compatible with $\omega_1 j_3$.

- But [if a child^{u2*} bites you]^{p2*}
- ⁽⁴⁾ **if**($r, p_2, [p_2: u_2 | \text{child}_{p_2}\{u_2\}, \text{bite}_{p_2}\{u_2, \text{you}\}]$); ⁽⁵⁾ [$r: \xi_0, \omega_0 | \xi_0 \equiv u_2, \omega_0 = p_2$];
 I won't _{ω_0, ω_1}
^(5?) [_ **not** _{ω_0, ω_1}]

	j_3	j_4	j_5
me	$\lambda w.john$	\rightarrow	\rightarrow
you	$\lambda w.bill$	\rightarrow	\rightarrow
r	$\lambda w \in K.K$	\rightarrow	\rightarrow
u_1	$\lambda w.u_1 j_1 w = \lambda w.\mathbf{d}_1 w$ s.t. ($\text{dog}_{p_1}\{u_1\}, \text{bite}_{p_1}\{u_1, \text{you}\}$) j_1	\rightarrow	\rightarrow
u_2	?	$\lambda w.u_2 j_4 w = \lambda w.\mathbf{c}_2 w$ s.t. ($\text{child}_{p_2}\{u_2\}, \text{bite}_{p_2}\{u_2, \text{you}\}$) j_3	\rightarrow
p_1	$\lambda w \in K.\min_{j_1, w} \mathbf{DB}$	\rightarrow	\rightarrow
p_2	?	$\lambda w \in K.\min_{j_4, w} \mathbf{CB}$	\rightarrow
ξ_0	$\lambda h \lambda w.\mathbf{d}_1 w$	\rightarrow	$\lambda h \lambda w.\mathbf{c}_2 w$
ω_0	$\lambda h \lambda w \in K.\min_{j_1, w} \mathbf{DB}$	\rightarrow	$\lambda h \lambda w \in K.\min_{j_4, w} \mathbf{CB}$
ω_1	$\lambda h \lambda w' \in \cup_w \omega_0 h w.$ $\min_{h, w'} \text{shoot}\{me, \xi_0\}$	\rightarrow	\rightarrow

^(5?) tests whether j_5 satisfies the test for **not** _{ω_0, ω_1} — i.e., whether $\omega_0 j_5$ is }, —inconsistent with $\omega_1 j_5$.