

Logic for Exact Entailment

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Abstract: An *exact truthmaker* for A is a state which, as well as guaranteeing A 's truth, is wholly relevant to it. States with parts irrelevant to whether A is true do not count as exact truthmakers for A . Giving semantics in this way produces a very unusual consequence relation, on which conjunctions do not entail their conjuncts. This feature makes the resulting logic highly unusual. In this paper, we set out formal semantics for exact truthmaking and characterise the resulting notion of entailment, showing that it is compact and decidable. We then investigate the effect of various restrictions on the semantics. We also formulate a sequent-style proof system for exact entailment and give soundness and completeness results.

Keywords: Truthmaking, exact entailment, non-classical logic, semantics, mereology, sequent calculus

I Introduction

There are a number of different ways in which a state or fact can be said to be a truthmaker for a sentence. It can simply necessitate the sentence; or it can necessitate the sentence while being partially relevant to its truth; or it can necessitate the sentence while being wholly relevant to its truth. Our interest in the present paper is in the third, *exact*, mode of truthmaking.

The notion of exact truthmaking has lately been applied to a number of different topics in philosophy and linguistics (Fine 2017) and it has natural affinities with the notion of *ground* in metaphysics. Given the significance of the notion, it is therefore of interest to determine the logic to which it gives rise. If truthmaking is taken to be wholly relevant, as on the exact model, rather than simply a matter of necessitation, as on the classical model, then what will be the resulting notion of entailment and how will it behave?

It turns out that this question is not altogether unambiguous. When we have the entailment of one formula by another, we may simply say that the one formula A exactly entails the other C when every exact truthmaker for A is an exact truthmaker for C . But when several formulas A_1, A_2, \dots are taken to entail another C , there are two different ways in which we might proceed. We might say, on a *distributive* reading, that every truthmaker for each of A_1, A_2, \dots should be a truthmaker for C ; or we might say, on a *collective* reading, that every truthmaker for the conjunction $A_1 \wedge A_2 \wedge \dots$ of A_1, A_2, \dots should be a truthmaker for C . These two notions of entailment will coincide in the classical case but not in the

* The paper arose in the following way. Mark Jago initially wrote a paper on the topic. This contained the characterisation theorem, but proved in a somewhat complicated way. He later learned of Kit Fine's related unpublished work on the collective notion of exact entailment; and they decided to join forces, thereby extending some of their previous results and simplifying some of the proofs.

exact case. For A, B will exactly entail A in the distributive sense of entailment but not in the collective sense, since there is, in general, no guarantee that an exact truthmaker for $A \wedge B$ will be an exact truthmaker for A . Since A entails A (in either sense), the collective sense of entailment, in contrast to the distributive sense, will not be monotonic.

The present paper focuses on the first, distributive, sense of exact entailment and is largely concerned with the special problems which arise when the same state is taken to be a truthmaker for different formulas. These problems are partly proof theoretic in character, since we are no longer entitled to infer from the fact that A, B exactly entails C that $A \wedge B$ exactly entails C . But they are also partly semantic, since it is not altogether clear what is required of a state when it is taken to be a truthmaker for two different formulas, such as $A \wedge B$ and $B \wedge C$.

One philosophical motivation for this distributive, truthmaker-sharing notion of entailment comes from multiple realizability, as in the philosophy of mind. Suppose mental statement M has both physical and non-physical possible realizers, but we want to focus on its physical realizers. These are the states which are truthmakers for both M and the statement P that there exist physical states (or, if you prefer, the infinite disjunction of all physical statements). We can conceptualise P as a condition on realizers for M and investigate the exact consequences of P and M , taken as distributive premises. Similar examples arise with determinable properties and conditions on their determinates.

A different kind of use arises in the investigation of *trivial truth*, where a truth is trivial in the sense that it requires nothing substantive to make it true (or, as we prefer to say, when it is made true by the *null state*). It is plausible, for example, that $A \rightarrow A$ is trivial in this sense, whereas $A \wedge \neg A$ is not. For the latter in general requires something substantive to make it true: a substantive truthmaker either for A or for $\neg A$; whereas $A \rightarrow A$ requires not even that. We can introduce a constant \top , by definition made true by every state, and investigate the consequences of distributive premises A and \top . If \perp (by definition made true by no state) is not a consequence, then A is a trivial truth in the intended sense. (We do not investigate \rightarrow, \top , or \perp further in this paper.)

However, our interest in the distributive notion of entailment is as much due to logical as to philosophical curiosity. The single-premise notion of exact entailment is already of great interest and so the question arises as to how should it be extended to the multi-premise case. If one holds that the logical notion of entailment should be monotonic in its premises, then the distributive notion presents itself as the obvious choice.

A rough outline of the paper is as follows. §2 presents the basic semantic framework and defines the relevant notions of exact truthmaking and exact entailment. §3 defines ‘selections’, the syntactic counterparts of truthmakers, and introduces the corresponding notion of a canonical model. §4 is central to the whole paper; it gives a characterisation of exact entailment in terms of selections. Of perhaps special interest is the method of proof, which depends upon defining a congruence on a canonical model, in something like the same way in which ‘filtrations’ are defined in modal logic. §5 applies the characterisation result to establish decidability and compactness. §6 and §7 consider various

further constraints that might be imposed on our models, and investigate the question of whether these further constraints result in any changes to the logic. §8 presents a sequent calculus, which is somewhat more complicated than usual, since A, B on the left of a sequent cannot be interpreted conjunctively. We therefore require two ‘structural’ connectives, one interpreted distributively and the other conjunctively. Finally, §9 establishes soundness and completeness for the system, and the eliminability of (CUT).

2 Exact Truthmaker Semantics

It is characteristic of exact truthmaking that truthmakers for a conjunction are not in general truthmakers for its conjuncts. A truthmaker for $A \wedge B$ is the *fusion* of a truthmaker for A and a truthmaker for B . We here have in mind the usual mereological notion of fusion, according to which a fusion is a structureless whole formed from its component parts (Varzi 2016). Writing $s \sqcup t$ for the fusion of s and t , we thus have:

s truthmakes $A \wedge B$ if and only if, for some t, u where t truthmakes A and u truthmakes B , $s = t \sqcup u$.

This is, in essence, van Fraassen’s clause for conjunction (1969, 484).

What should we say about disjunctions? A disjunction is made true by whatever makes at least one of its disjuncts true, so we might say:

s truthmakes $A \vee B$ if and only if either s truthmakes A or s truthmakes B .

However, this seems to exclude a further way of making a disjunction true, namely, by being made up of parts which individually make the disjuncts true. After all, the state of affairs *that Anna is walking and Bec is sitting* is wholly relevant to the truth of ‘Anna is walking or Bec is sitting’, even if it is overkill. So we may instead say:

s truthmakes $A \vee B$ if and only if s truthmakes A , s truthmakes B , or $s = t \sqcup u$ for some truthmakers t for A and u for B .

On the latter conception (though not on the former), truthmakers for $A \wedge B$ are also truthmakers for $A \vee B$, and so (if we define entailment as truthmaker-preservation) $A \wedge B$ will entail $A \vee B$. To keep things simple, we will adopt the latter clause for disjunctions here. Nevertheless, all of the results that follow will go through if we adopt the former, under a suitable modification of definition 6 in §3.

We have said what the truthmakers for conjunctions and disjunctions are, so we now need to say something about their falsemakers too. But this is straightforward. A falsemaker for $A \wedge B$ is something which falsemakes A , or B , or else is the fusion of such falsemakers; a falsemaker for $A \vee B$ is a fusion of a falsemaker for A and a falsemaker for B ; and a falsemaker for $\neg A$ is a truthmaker for A (while a truthmaker for $\neg A$ is a falsemaker for A).

Having given an overview of our semantics, it is time to make it more precise.

Definition 1 (Syntax). Let \mathcal{P} be a set of sentence letters. The language \mathcal{L} is then the smallest set containing \mathcal{P} closed under 1-place \neg and 2-place \wedge and \vee . Λ is the set of *literals* over \mathcal{P} , i.e. $\mathcal{P} \cup \{\neg p : p \in \mathcal{P}\}$. Let $\leq_{\mathcal{L}}$ be any total order on \mathcal{L} . We define $\wedge\{A_1, \dots, A_n\} = (A_1 \wedge (A_2 \wedge \dots \wedge A_n) \dots)$, where $A_i \leq_{\mathcal{L}} A_j$ iff $i \leq j$. (We shall see below that \wedge is commutative and associative, and so brackets and order of conjuncts is semantically irrelevant.)

We take \mathcal{P} (and hence \mathcal{L} and Λ) to be fixed throughout.

Definition 2 (Frames and models). Frames are structures $\langle S, \sqsubseteq \rangle$ where S is a set of entities (states) and \sqsubseteq is a partial order (reflexive, transitive, and anti-symmetric), such that each pair $s, t \in S$ has a least upper bound in S , denoted $s \sqcup t$. An *exact truthmaking model* is a structure $\langle S, \sqsubseteq, |\cdot|^+, |\cdot|^- \rangle$ where $\langle S, \sqsubseteq \rangle$ is a frame and $|\cdot|^+$ and $|\cdot|^-$ are valuation functions from sentence letters \mathcal{P} to 2^S , closed under \sqcup : if $s, t \in |p|^+$ then $s \sqcup t \in |p|^+$, and similarly for $|p|^-$.

Definition 3 (Exact truthmaking and falsemaking). Given a exact truthmaking model $M = \langle S, \sqsubseteq, |\cdot|^+, |\cdot|^- \rangle$ (which we leave implicit), *exact truthmaking* \Vdash and *exact falsemaking* $\dashv\vdash$ relations are then defined by double recursion as follows:

$$\begin{aligned}
s \Vdash p & \text{ iff } s \in |p|^+ \\
s \dashv\vdash p & \text{ iff } s \in |p|^- \\
s \Vdash \neg A & \text{ iff } s \dashv\vdash A \\
s \dashv\vdash \neg A & \text{ iff } s \Vdash A \\
s \Vdash A \wedge B & \text{ iff } \exists tu (s = t \sqcup u \ \& \ t \Vdash A \ \& \ u \Vdash B) \\
s \dashv\vdash A \wedge B & \text{ iff } s \dashv\vdash A \text{ or } s \dashv\vdash B \text{ or} \\
& \quad \exists tu (s = t \sqcup u \ \& \ t \dashv\vdash A \ \& \ u \dashv\vdash B) \\
s \Vdash A \vee B & \text{ iff } s \Vdash A \text{ or } s \Vdash B \text{ or} \\
& \quad \exists tu (s = t \sqcup u \ \& \ t \Vdash A \ \& \ u \Vdash B) \\
s \dashv\vdash A \vee B & \text{ iff } \exists tu (s = t \sqcup u \ \& \ t \dashv\vdash A \ \& \ u \dashv\vdash B)
\end{aligned}$$

Given a set of formulas Γ , we define $s \Vdash \Gamma$ ($s \dashv\vdash \Gamma$) just in case $s \Vdash B$ ($s \dashv\vdash B$) for each $B \in \Gamma$. We extend the $|\cdot|^+$ and $|\cdot|^-$ notation to all formulas A by setting $|A|^+ = \{s \mid s \Vdash A\}$ and $|A|^- = \{s \mid s \dashv\vdash A\}$.

Given this semantics, no formula is valid (in the sense of being true at all states in all models), and any set of formulas is satisfiable (just consider a state which both truthmakes and falsemakes every sentence letter p). We characterise our logic in terms of the entailments it supports. As usual, we treat entailment as the preservation of truth from premises to conclusion. But in so doing, how should we conceptualise our premises? As mentioned in §1, we could treat them *collectively*, so that entailment amounts to preservation of truth from the conjoined premises to the conclusion. Alternatively, we could treat our premises *distributively*, so that entailment amounts to preservation of truth from each individual premise to the conclusion. These notions coincide on single-premise entailments, but are not equivalent when we have multiple premises.

When there are no further restrictions on the models we use, the conjunctive approach will give us a nonmonotonic entailment relation. A will conjunctively-entail A , but $\{A, B\}$ will not conjunctively-entail A (since $A \wedge B$ does not, in general, conjunctively-entail A .) [Fine \(2016\)](#) investigates this conjunctive notion of entailment in combination with various restrictions on models. Accordingly, we shall not say any more about it here.

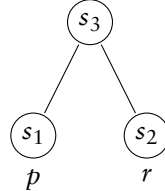
We shall focus on the distributive notion of entailment, abbreviated as ‘ \models ’, which we define as follows:

Definition 4 (Exact Truthmaking Entailment). $\Gamma \models A$ iff, for any model M and any state s of M , $M, s \Vdash A$ whenever $M, s \Vdash \Gamma$.

Exact equivalence is defined as two-way exact entailment. As the reader can easily check, exact entailment satisfies the following equivalences and entailments:

$$\begin{array}{ll}
 A \wedge B \models B \wedge A & A \vee B \models B \vee A \\
 A \wedge (B \wedge C) \models (A \wedge B) \wedge C & A \vee (B \vee C) \models (A \vee B) \vee C \\
 A \wedge (B \vee C) \models (A \wedge B) \vee (A \wedge C) & A \vee (B \wedge C) \models (A \vee B) \wedge (A \vee C) \\
 A \wedge A \models A & A \vee A \models A \\
 \neg(A \wedge B) \models \neg A \vee \neg B & \neg(A \vee B) \models \neg A \wedge \neg B \\
 A, B \models A \wedge B & A \models A \vee B \\
 \neg\neg A \models A &
 \end{array}$$

Note that distribution of \vee over \wedge is not an equivalence, for $(p \vee q) \wedge (p \vee r) \not\models p \vee (q \wedge r)$. To see this, take the model:



In this model, $s_1 \Vdash p \vee q$ and $s_2 \Vdash p \vee r$, hence $s_3 \Vdash (p \vee q) \wedge (p \vee r)$, but $s_3 \not\Vdash p \vee (q \wedge r)$. Given the failure of \vee to distribute over \wedge , our semantics does not give rise to a \wedge, \vee -distributive lattice. This is precisely what makes reasoning about the semantics more difficult (and more interesting) than would otherwise be the case.

Note also that, since \wedge is commutative and associative, it is harmless to write $\wedge\{A_1, \dots, A_n\}$ as $A_1 \wedge \dots \wedge A_n$, and to ignore the ordering $\leq_{\mathcal{L}}$.

We now turn to some results characterising the exact semantics, beginning in the next section and culminating, in §4, with a characterisation theorem for exact truthmaker entailment.

3 Syntactic Selections and the Canonical Model

In this section, we describe a way to extract from a sentence A a description of the definite ways a truthmaker for A should be. These descriptions take the form of a set of literals. Intuitively, a description $\{\lambda_1, \dots, \lambda_n\}$ describes a state s which is the fusion of states s_1, \dots, s_n , where each s_i truthmakes literal λ_i . We will call such a description, qua set of literals, a *selection* from A .

As selections provide us with a syntactic means to reason about our semantics, it is natural to begin our discussion by constructing a corresponding canonical model.

Definition 5 (Canonical Model). Let $\mathfrak{M} = \langle \mathfrak{S}^{\mathfrak{M}}, \sqsubseteq^{\mathfrak{M}}, |\cdot|^{+\mathfrak{M}}, |\cdot|^{-\mathfrak{M}} \rangle$ where:

- $\mathfrak{S}^{\mathfrak{M}} = 2^\Lambda$, the set of all sets of literals;
- $\sqsubseteq^{\mathfrak{M}}$ is \subseteq restricted to $\mathfrak{S}^{\mathfrak{M}}$;
- $|p|^{+\mathfrak{M}} = \{\{p\}\}$;
- $|p|^{-\mathfrak{M}} = \{\{\neg p\}\}$.

\mathfrak{M} is clearly a genuine model.

Now we can define our notion of a *selection* from A .

Definition 6 (Selections). Given a formula A , a set of literals x is a *selection from* A just in case $\mathfrak{M}, x \Vdash A$ (where \mathfrak{M} is the canonical model). The set of all selections from A , $\mathcal{S}A$, is $\{x \mid \mathfrak{M}, x \Vdash A\}$. We extend the terminology to sets of sentences Γ : a selection from Γ contains one selection from each $A \in \Gamma$. We define the set of all selections from Γ , $\mathcal{S}\Gamma$, as follows. When $\Gamma = \{A_1, A_2, \dots\}$ for distinct A_1, A_2, \dots , $\mathcal{S}\Gamma$ is the collection of all sets $\{x_1, x_2, \dots\}$, for each x_i a selection from A_i .

We note an equivalent characterisation of $\mathcal{S}A$:

$$\begin{aligned} \mathcal{S}p &= \{\{p\}\} \text{ and } \mathcal{S}\neg p = \{\{\neg p\}\} \\ \mathcal{S}(A \wedge B) &= \{x \cup y \mid x \in \mathcal{S}A, y \in \mathcal{S}B\} \\ \mathcal{S}\neg(A \wedge B) &= \mathcal{S}\neg A \cup \mathcal{S}\neg B \cup \mathcal{S}(\neg A \wedge \neg B) \\ \mathcal{S}(A \vee B) &= \mathcal{S}A \cup \mathcal{S}B \cup \mathcal{S}(A \wedge B) \\ \mathcal{S}\neg(A \vee B) &= \{x \cup y \mid x \in \mathcal{S}\neg A, y \in \mathcal{S}\neg B\} \\ \mathcal{S}\neg\neg A &= \mathcal{S}A \end{aligned}$$

This presentation brings out the similarity between our notion of a selection and van Fraassen's definition (1969, 484) of truthmaking and falsmaking sets.

The following lemmas show that selections are closed under union and, more importantly, establish the relationship between A 's selections and the states that truthmake A .

Lemma 3.1. *For any model M and states s, u in M , if $s \Vdash A$ and $u \Vdash A$ then $s \sqcup u \Vdash A$.*

Proof: By induction on A . Assume $s \Vdash A$ and $u \Vdash A$. The base case holds by definition 2. So assume the result holds for all B less complex than A and consider these cases.

- $A := B \wedge C$. Then $s = s_1 \sqcup s_2$, $u = u_1 \sqcup u_2$, where $s_1 \Vdash B$, $s_2 \Vdash C$, $u_1 \Vdash B$, and $u_2 \Vdash C$. By hypothesis, $s_1 \sqcup u_1 \Vdash B$ and $s_2 \sqcup u_2 \Vdash C$, so $s_1 \sqcup u_1 \sqcup s_2 \sqcup u_2 \Vdash B \wedge C$, hence $s \sqcup u \Vdash B \wedge C$.
- $A := B \vee C$. Then (i) $s \Vdash B$, (ii) $s \Vdash C$, or (iii) $s = s_1 \sqcup s_2$ where $s_1 \Vdash B$ and $s_2 \Vdash C$; and (iv) $u \Vdash B$, (v) $u \Vdash C$, or (vi) $u = u_1 \sqcup u_2$ where $u_1 \Vdash B$ and $u_2 \Vdash C$. If (i) & (iv), then by hypothesis, $s \sqcup u \Vdash B$ and so $s \sqcup u \Vdash B \vee C$. If (i) & (v), then by definition $s \sqcup u \Vdash B \vee C$. If (i) & (vi), then by hypothesis, $s \sqcup u_1 \Vdash B$, and so $(s_1 \sqcup u_1) \sqcup u_2 \Vdash B \vee C$, hence $s \sqcup u \Vdash B \vee C$. The (ii) & (iv), (ii) & (v), (ii) & (vi), (iii) & (iv), and (iii) & (v) cases are similar. Finally, if (iii) and (vi), then by hypothesis, $s_1 \sqcup u_1 \Vdash B$ and $s_2 \sqcup u_2 \Vdash C$, so $(s_1 \sqcup u_1) \sqcup (s_2 \sqcup u_2) \Vdash B \vee C$ and hence $s \sqcup u \Vdash B \vee C$.
- The $A := \neg(A \wedge B)$ and $A := \neg(A \vee B)$ cases are similar, and the $A := \neg\neg B$ case is trivial. ■

Corollary 3.2. *If $x, y \in SA$ then $x \cup y \in SA$.*

Proof: Suppose $x, y \in SA$. Then by definition 6, $\mathfrak{M}, x \Vdash A$ and $\mathfrak{M}, y \Vdash A$ (where \mathfrak{M} is the canonical model). By lemma 3.1, we have $\mathfrak{M}, x \cup y \Vdash A$. Since $x \cup y = x \cup y$ in \mathfrak{M} , we have $\mathfrak{M}, x \cup y \Vdash A$ and hence $x \cup y \in SA$. ■

Lemma 3.3 (Selection lemma). *For any formula A , model M and state s in M :*

$$s \Vdash A \text{ iff, for some } x \in SA, s \Vdash \wedge x.$$

Proof, left-to-right: The proof is by induction on the complexity of A . Assume $s \Vdash A$. If A is a literal p or $\neg p$ then SA is either $\{\{p\}\}$ or $\{\{\neg p\}\}$. So for any $x \in SA$, $\wedge x = A$ and the result holds. Now assume that the result holds for all B less complex than A , and consider these cases:

- If $A := A_1 \wedge A_2$ then $s = s_1 \sqcup s_2$ where $s_1 \Vdash A_1$ and $s_2 \Vdash A_2$. By hypothesis, there are $x \in SA_1$ and $y \in SA_2$ such that $s_1 \Vdash \wedge x$ and $s_2 \Vdash \wedge y$. So $s \Vdash (\wedge x) \wedge (\wedge y)$ and hence $s \Vdash \wedge(x \cup y)$. Since $x \cup y \in SA$ (corollary 3.2), the result holds.
- If $A := A_1 \vee A_2$ then either (i) $s \Vdash A_1$, (ii) $s \Vdash A_2$ or (iii) $s = s_1 \sqcup s_2$ where $s_1 \Vdash A_1$ and $s_2 \Vdash A_2$. If (i) then, by hypothesis, there is some $x \in SA_1$ such that $s \Vdash \wedge x$. So by definition, $x \in \mathcal{S}(A_1 \vee A_2)$. Case (ii) is similar. If (iii) then by hypothesis there are $x_1 \in SA_1$ and $x_2 \in SA_2$ such that $s_1 \Vdash \wedge x_1$ and $s_2 \Vdash \wedge x_2$. Then (reasoning as above) $s \Vdash \wedge(x \cup y)$ and $x \cup y \in \mathcal{S}(A_1 \wedge A_2)$. But in general, $\mathcal{S}(B \wedge C) \subseteq \mathcal{S}(B \vee C)$ (definition 6), and hence $x \cup y \in SA$.
- The cases for $A := \neg(A \vee B)$ and $A := \neg(A \wedge B)$ are similar to the cases above, respectively, and the case for $A := \neg\neg A$ is trivial.

Right-to-left: Also by induction on the complexity of A . Assume there's some $x \in \mathcal{S}A$ such that $s \Vdash \wedge x$. As before, if A is a literal the result is immediate. So assume that the result holds for all B less complex than A and consider these cases:

- If $A := A_1 \wedge A_2$ then by definition 6, for some $x_1 \in \mathcal{S}A_1$ and $x_2 \in \mathcal{S}A_2$, $x = x_1 \sqcup x_2$. Given that $s \Vdash \wedge(x_1 \sqcup x_2)$, we have $s \Vdash (\wedge x_1) \wedge (\wedge x_2)$ and so there are s_1, s_2 such that $s = s_1 \sqcup s_2$, $s_1 \Vdash \wedge x_1$ and $s_2 \Vdash \wedge x_2$. By hypothesis, $s_1 \Vdash A_1$ and $s_2 \Vdash A_2$, and so $s \Vdash A$.
- If $A := A_1 \vee A_2$ then, by definition 6, either (i) $x \in \mathcal{S}A_1$, (ii) $x \in \mathcal{S}A_2$ or (iii) $x \in \mathcal{S}(A_1 \wedge A_2)$. If (i) then, by hypothesis, $s \Vdash A_1$ and hence $s \Vdash A$. Similarly, if (ii) then $s \Vdash A_2$ and hence $s \Vdash A$. And if (iii) then there are s_1, s_2 such that $s = s_1 \sqcup s_2$, $s_1 \Vdash \wedge x_1$ and $s_2 \Vdash \wedge x_2$. By hypothesis, $s_1 \Vdash A_1$ and $s_2 \Vdash A_2$, and so $s \Vdash A$.
- Again, the cases for $A := \neg(A \vee B)$ and $A := \neg(A \wedge B)$ are similar to the cases above, respectively, and the case for $A := \neg\neg A$ is trivial. ■

4 Characterisation of Exact Entailment

In this section, we show how to characterise exact entailment in terms of a syntactic relationship between the premises and the conclusion. The conclusion must be built from selections taken from the premises, in a certain way, in order for an exact entailment to hold. We make this relationship precise in our characterisation theorem 4.8 below. Once we've established this theorem, compactness and decidability are straightforward.

We proceed by showing how to transform a model in to a congruent model. Intuitively, the congruent model takes certain states in the original model and treats them as a single state. Our strategy is then to build a counter-model to a purported entailment by identifying all the states which truthmake the premises, and showing that this state does not truthmake the conclusion. The following definitions and lemmas give the details.

Definition 7 (Overlap, difference, and convexity). A state \square is *null* just in case $\square \sqsubseteq s$ for every s . If a null state exists, it is unique, and we reserve the name ' \square ' for it. States s and u overlap iff some state $t \neq \square$ is a part of both: $t \sqsubseteq s$ and $t \sqsubseteq u$. The greatest lower bound of s and u , if there is one, is denoted $s \sqcap u$. The *difference* of states s and u , written $s - u$, is the unique state t (if there is one) such that any v is a part of t iff v is a part of s but does not overlap u . (So, $s - u$ is the \sqsubseteq -greatest part of s which does not overlap u , if there is one.) A set of states S is *closed under difference* iff $s - u \in S$ whenever $s, u \in S$. A set of states S is *convex* iff $t \in S$ whenever $s, u \in S$ and $s \sqsubseteq t \sqsubseteq u$.

Note that $s - \square = s$ and $s - s = \square$, for any state s . If S is closed under difference, then $s - s \in S$ for any $s \in S$, and so $\square \in S$.

For technical reasons, we will occasionally need to rely on models containing the null state. But this is a harmless move for, as the following lemma shows, we can always add the null state to the bottom of a model without changing the model elsewhere.

Lemma 4.1 (Null state). *Let $M = \langle S, \sqsubseteq, |\cdot|^+, |\cdot|^- \rangle$ and $M^\square = \langle S \cup \{\square\}, \sqsubseteq^\square, |\cdot|^+, |\cdot|^- \rangle$, where $s \sqsubseteq^\square u$ iff either $s \sqsubseteq u$ or $s = \square$. Then, for any $s \in S$: $M, s \Vdash A$ iff $M^\square, s \Vdash A$.*

Proof: Given lemma 3.3, we need show only that M and M^\square agree on any conjunction of literals at every $s \in S$: $M, s \Vdash l_1 \wedge \dots \wedge l_n$ iff $M^\square, s \Vdash l_1 \wedge \dots \wedge l_n$. In either model, $s \Vdash l_1 \wedge \dots \wedge l_n$ just in case there are states s_1, \dots, s_n such that $s = s_1 \sqcup \dots \sqcup s_n$ and, for each $i \leq n$, $s_i \Vdash l_i$. Given that $\square \notin V^+p$ and $\square \notin V^-p$ for any sentence letter p , $s_i \Vdash l_i$ implies $s_i \in S$. And since M and M^\square agree on all literals at every $s \in S$, the result follows. ■

Definition 8 (Congruence relation). Let $M = \langle S, \sqsubseteq, |\cdot|^+, |\cdot|^- \rangle$ be a model with S closed under arbitrary fusions ($\sqcup U \in S$ for any $U \subseteq S$) and pairwise difference. Let $C \subseteq S$ be a convex set closed under \sqcup . We define \equiv_C to be the smallest equivalence relation on S such that:

- (a) If $s, u \in C$ then $s \equiv_C u$; and
- (b) If $s \equiv_C s'$ and $u \equiv_C u'$ then $s \sqcup u \equiv_C s' \sqcup u'$.

(Note that there must exist a smallest such relation.) We will write $[s]_C$ for $\{u \mid u \equiv_C s\}$ and boldface $\mathbf{s}, \mathbf{u}, \dots$ for arbitrary equivalence classes.

The following lemma gives an equivalent characterisation of \equiv_C .

Lemma 4.2. *Let M and C be as above, and let $s \approx_C u$ whenever: either $s = u$; or else (i) there are $c_1, c_2 \in C$ such that $c_1 \sqsubseteq s$ and $c_2 \sqsubseteq u$ and (ii) $s - \sqcup C = u - \sqcup C$. Then $s \approx_C u$ iff $s \equiv_C u$.*

Proof, left-to-right: Assume $s \approx_C u$. If $s = u$ then trivially, $s \equiv_C u$; so assume instead that $s \neq u$. Then $s - \sqcup C = u - \sqcup C$ and hence $s - \sqcup C \equiv_C u - \sqcup C$. Moreover, there are $c_1, c_2 \in C$ with $c_1 \sqsubseteq s$ and $c_2 \sqsubseteq u$. Hence $c_1 \sqsubseteq (s \sqcap \sqcup C) \sqsubseteq \sqcup C$. Since C is \sqcup -closed and convex, we have $\sqcup C \in C$ and hence $(s \sqcap \sqcup C) \in C$. Similarly, we have $(u \sqcap \sqcup C) \in C$ and hence $(s \sqcap \sqcup C) \equiv_C (u \sqcap \sqcup C)$. This gives us $(s - \sqcup C) \sqcup (s \sqcap \sqcup C) \equiv_C (u - \sqcup C) \sqcup (u \sqcap \sqcup C)$ and hence $s \equiv_C u$.

Right-to-left: We show \approx_C satisfies clauses (a) and (b) of definition 8. If $s, u \in C$ then condition (i) is satisfied with $c_1 = s$ and $c_2 = u$ and condition (ii) is satisfied, since $s - \sqcup C = u - \sqcup C$. Hence \approx_C satisfies clause (a). Now assume $s \approx_C s'$ and $u \approx_C u'$. If $s = s'$ but $u \neq u'$, then by definition there are $c_1, c_2 \in C$ with $c_1 \sqsubseteq u$ and $c_2 \sqsubseteq u'$, and $u - \sqcup C = u' - \sqcup C$. Then $c_1 \sqsubseteq s \sqcup u$, $c_2 \sqsubseteq s' \sqcup u'$, and $(s \sqcup u) - \sqcup C = (s - \sqcup C) \sqcup (u - \sqcup C) = (s' - \sqcup C) \sqcup (u' - \sqcup C) = (s' \sqcup u') - \sqcup C$, and so $s \sqcup u \approx_C s' \sqcup u'$. By similar reasoning, $s \sqcup u \approx_C s' \sqcup u'$ if $u = u'$ but $s \neq s'$. So now suppose $s \neq s'$ and $u \neq u'$. Then by definition there are $c_1, c_2, c_3, c_4 \in C$ with $c_1 \sqsubseteq s$, $c_2 \sqsubseteq u$, $c_3 \sqsubseteq s'$ and $c_4 \sqsubseteq u'$. So $c_1 \sqcup c_2 \sqsubseteq s \sqcup u$ and $c_3 \sqcup c_4 \sqsubseteq s' \sqcup u'$ and,

since C is \sqcup -closed, we have $c_1 \sqcup c_2, c_3 \sqcup c_4 \in C$. Moreover, from condition (ii), $s - \sqcup C = s' - \sqcup C$ and $u - \sqcup C = u' - \sqcup C$, hence

$$(s - \sqcup C) \sqcup (u - \sqcup C) = (s' - \sqcup C) \sqcup (u' - \sqcup C)$$

so

$$(s \sqcup u) - \sqcup C = (s' \sqcup u') - \sqcup C$$

and hence $s \sqcup u \approx_C s' \sqcup u'$. Hence \approx_C satisfies clause (b).

It remains only to show that \approx_C is an equivalence relation. It is clearly reflexive and symmetrical; so suppose $s \approx_C t$ and $t \approx_C u$. If either $s = t$ or $t = u$ then $s \approx_C u$; so suppose this is not the case. Then by definition, we have $c_1, c_2, c_3 \in C$ with $c_1 \sqsubseteq s$, $c_2 \sqsubseteq t$, and $c_3 \sqsubseteq u$; and $s - \sqcup C = t - \sqcup C = u - \sqcup C$, hence $s \approx_C u$. It follows that \approx_C is an equivalence relation and hence that $s \equiv_C u$ implies $s \approx_C u$. ■

Definition 9. Let M and C be as above. We define an operator \sqcup^C on equivalence classes of states by setting $\mathbf{s} \sqcup^C \mathbf{u} = \bigcup_{\substack{s \in \mathbf{s} \\ u \in \mathbf{u}}} [s \sqcup u]_C$.

Lemma 4.3. $[s]_C \sqcup^C [u]_C = [s \sqcup u]_C$.

Proof: Suppose $s, s' \in \mathbf{s}$ and $u, u' \in \mathbf{u}$. Then $s \equiv_C s'$ and $u \equiv_C u'$, hence by definition, $s \sqcup u \equiv_C s' \sqcup u'$ and so $s' \sqcup u' \in [s \sqcup u]_C$. It follows that, for any $s \in \mathbf{s}$ and $u \in \mathbf{u}$:

$$\bigcup_{\substack{s' \in \mathbf{s} \\ u' \in \mathbf{u}}} [s' \sqcup u']_C = [s \sqcup u]_C$$

and hence that $[s]_C \sqcup^C [u]_C = [s \sqcup u]_C$. ■

Definition 10 (Congruent structures). Let M and C be as above. We transform M into a congruent structure, $M^C = \langle S^C, \sqsubseteq^C, |\cdot|^{+C}, |\cdot|^{-C} \rangle$, where:

- $S^C = \{[s]_C \mid s \in S\}$
- $\mathbf{s} \sqsubseteq^C \mathbf{u}$ iff $\mathbf{s} \sqcup^C \mathbf{u} = \mathbf{u}$
- $|\mathbf{p}|^{+C} = \{[s]_C \mid s \in |\mathbf{p}|^+\}$
- $|\mathbf{p}|^{-C} = \{[s]_C \mid s \in |\mathbf{p}|^-\}$

Intuitively, a congruent structure treats all the elements of C as a single state, and makes whatever identifications thereby follow.

Lemma 4.4. *Let M and C be as above. Then M^C is a model.*

Proof: Given lemma 4.3, it follows that \sqcup^C is commutative, associative and idempotent and hence that \sqsubseteq^C is a partial order on S^C . Moreover, lemma 4.3 guarantees that $[s]_C \sqcup^C [u]_C \in S^C$ whenever $[s]_C, [u]_C \in S^C$. It follows, by definition 2, that M^C is a model. ■

Lemma 4.5. *Let M^C be as above. For any state u in M^C , if there is no $s \in C$ such that $s \sqsubseteq u \sqsubseteq \sqcup C$, then for no $s \in C$ is $s \equiv_C u$.*

Proof: By contraposition. Suppose there is some $s \in C$ such that $s \equiv_C u$. Then by lemma 4.2, $s \approx_C u$. If $s = u$ then the result follows immediately; so suppose $s \neq u$. Then by definition of \approx_C , (i) there is some $c \in C$ such that $c \sqsubseteq u$ and (ii) $s - \sqcup C = u - \sqcup C$. Since $s \in C$, we have $s \sqsubseteq \sqcup C$ and hence $u \sqsubseteq \sqcup C$, which gives us $c \sqsubseteq u \sqsubseteq \sqcup C$. ■

Lemma 4.6 (Congruent models). *Let M and C be as in definition 10. We form the congruent model M^C . Then:*

$M^C, s \Vdash A$ iff there is some $u \in s$ such that $M, u \Vdash A$.

Proof, left-to-right: By induction on A . Suppose $M^C, s \Vdash A$. If $A := p$ then by definition, $s \in |p|^{+C} = \{[s]_C \mid s \in |p|^+\}$, hence for some $u \in s$, $u \in |p|^+$, and so $M, s \Vdash p$. Similarly, if $A := \neg p$ then $s \in |p|^{-C} = \{[s]_C \mid s \in |p|^-\}$, hence for some $u \in s$, $u \in |p|^-$, so $M, s \not\Vdash p$, and hence $M, s \Vdash \neg p$. Now assume the result holds for all B less complex than A .

- $A := A_1 \wedge A_2$. Then $s = s_1 \sqcup^C s_2$ where $M^C, s_1 \Vdash A_1$ and $M^C, s_2 \Vdash A_2$. So by hypothesis, there are $u_1 \in s_1$ and $u_2 \in s_2$ such that $M, u_1 \Vdash A_1$ and $M, u_2 \Vdash A_2$. Hence $M, u_1 \sqcup u_2 \Vdash A$. Then we have $s = s_1 \sqcup^C s_2 = [u_1]_C \sqcup^C [u_2]_C = [u_1 \sqcup u_2]_C^C$ (by lemma 4.3), and hence $u_1 \sqcup u_2 \in s$.
- $A := A_1 \vee A_2$. Then (i) $M^C, s \Vdash A_1$, (ii) $M^C, s \Vdash A_2$, or (iii) $s = s_1 \sqcup^C s_2$ where $M^C, s_1 \Vdash A_1$ and $M^C, s_2 \Vdash A_2$. If (i) then, by hypothesis, $M, u \Vdash A_1$, and hence $M, u \Vdash A$, for some $u \in s$. Similarly, if (ii) then $M, u \Vdash A_2$, and hence $M, u \Vdash A$, for some $u \in s$. If (iii) then, by the reasoning in the previous case, we have $u_1 \sqcup u_2 \in s$ such that $M, u_1 \Vdash A_1$ and $M, u_2 \Vdash A_2$, and hence $M, u_1 \sqcup u_2 \Vdash A$.
- The cases for $A := \neg(A \vee B)$ and $A := \neg(A \wedge B)$ are similar to the cases above, respectively, and the case for $A := \neg\neg A$ is trivial.

Right-to-left: Again, by induction on A . Assume $M, u \Vdash A$ for some $u \in s$. Then $s = [u]_C$. If $A := p$ then by definition, $u \in |p|^+$, so $[u]_C \in |p|^{+C}$, so $s \in |p|^{+C}$, and hence $M^C, s \Vdash p$. Similarly, if $A := \neg p$ then $u \in |p|^-$, so $s \in |p|^{-C}$, hence $M^C, s \not\Vdash p$ and so $M^C, s \Vdash \neg p$. Now assume the result holds for all B less complex than A .

- $A := A_1 \wedge A_2$. Then $u = u_1 \sqcup u_2$, where $M, u_1 \Vdash A_1$ and $M, u_2 \Vdash A_2$. By hypothesis, $M^C, [u_1]_C \Vdash A_1$ and $M^C, [u_2]_C \Vdash A_2$, and hence $M^C, [u_1]_C \sqcup^C [u_2]_C \Vdash A$. By lemma 4.3, $[u_1]_C \sqcup^C [u_2]_C = [u_1 \sqcup u_2]_C = [u]_C = s$, hence $M^C, s \Vdash A$.
- $A := A_1 \vee A_2$. Then (i) $M, u \Vdash A_1$, (ii) $M, u \Vdash A_2$, or (iii) $u = u_1 \sqcup u_2$ where $M, u_1 \Vdash A_1$ and $M, u_2 \Vdash A_2$. If (i) then, by hypothesis, $M^C, s \Vdash A_1$ and hence $M^C, s \Vdash A$. Similarly, if (ii) then $M^C, s \Vdash A_2$ and hence $M^C, s \Vdash A$. If (iii) then, by reasoning in the previous case, $M^C, [u_1]_C \Vdash A_1$ and $M^C, [u_2]_C \Vdash A_2$, hence $M^C, [u_1]_C \sqcup^C [u_2]_C \Vdash A$, and $[u_1]_C \sqcup^C [u_2]_C = s$. So $M^C, s \Vdash A$.

- Again, the cases for $A := \neg(A \vee B)$ and $A := \neg(A \wedge B)$ are similar to the cases above, respectively, and the case for $A := \neg\neg A$ is trivial. ■

We now form a congruence relation on our canonical model, transforming the latter into a congruent canonical model. Note that, since states in the canonical model are sets of sentences, the set of all such states is trivially closed under arbitrary fusions and difference; and we can always take a set of canonical model states S and close it under convexity and pairwise fusion. We use the resulting set of states, C , to form our convex canonical model.

Corollary 4.7. *Let $\mathfrak{M} = \langle \mathfrak{S}, \sqsubseteq, |\cdot|^+, |\cdot|^- \rangle$ be the canonical model, and $C \subseteq \mathfrak{S}$ be convex and closed under \sqcup . Form the congruent canonical model \mathfrak{M}^C . Then $\mathfrak{M}^C, s \Vdash A$ iff $s \cap SA \neq \emptyset$.*

Proof: From lemma 4.6 and lemma 3.3, we have $\mathfrak{M}^C, s \Vdash A$ iff $\mathfrak{M}, u \Vdash A$ for some $u \in s$ iff $\mathfrak{M}, u \Vdash \bigwedge x$ for some $u \in s$ and $x \in SA$. But by construction of \mathfrak{M} , this holds iff $x = u$ for some $u \in s$ and $x \in SA$ and hence iff $s \cap SA \neq \emptyset$. ■

Now for our characterisation theorem, which says the following. Suppose we have an entailment from premises Γ to conclusion A . Then, for any selection X from the premises, we must be able to find a selection y from the conclusion which lies between some specific $x \in X$ and X itself: $x \sqsubseteq y \sqsubseteq \bigcup X$. Intuitively, we may think of selections as describing specific truth-grounds for a sentence. So our theorem intuitively says: an entailment holds when, for any collection of truth-grounds for the premises, some truth-ground for the conclusion lies in-between one and all of those premise truth-grounds.

Let us illustrate the idea. Consider the entailment: $p, r \models (p \vee q) \wedge r$. The selections for p and r are just $\{p\}$ and $\{r\}$ (neither of which is a selection from $(p \vee q) \wedge r$). But $\{\{p\}, \{r\}\}$ is the only selection from the premise-set $\{p, r\}$ and $\{p, r\}$ is a selection from the conclusion. This gives us the inclusion relationship $\{p\} \sqsubseteq \{p, r\} \sqsubseteq \bigcup \{\{p\}, \{r\}\}$, which satisfies the theorem's condition on entailment, hence $p, r \models (p \vee q) \wedge r$.

Theorem 4.8 (Characterisation of \models). *$\Gamma \models A$ if and only if, for any $X \in \mathcal{S}\Gamma$, some $y \in SA$ and some $x \in X$: $x \sqsubseteq y \sqsubseteq \bigcup X$.*

Proof, left-to-right: We show the contrapositive. Assume that, for some $X \in \mathcal{S}\Gamma$ (which we keep fixed) and any $y \in SA$, there is no $x \in X$ such that $x \sqsubseteq y \sqsubseteq \bigcup X$. Now let C be the closure of X under \sqcup , $-$, and convexity. Then $\bigcup C = \bigcup X$ and, for any $z \in C$, there is some $x \in X$ with $x \sqsubseteq z$ and so, for any $y \in SA$, there is no $x \in C$ such that $x \sqsubseteq y \sqsubseteq \bigcup C$. Now let \mathfrak{M}^C be the congruent canonical model over C . Then C is a state of \mathfrak{M}^C , $C = [x]_C$ for any $x \in C$, and there is no $x \in C$ and $y \in SA$ such that $x \sqsubseteq y \sqsubseteq \bigcup C$. So, by lemma 4.5, for no $x \in C$ and $y \in SA$ do we have $x \equiv_C y$. It follows that $SA \cap C = \emptyset$ and so, by corollary 4.7, $\mathfrak{M}^C, C \not\Vdash A$. Moreover, for each $B \in \Gamma$, we have $SB \cap X \neq \emptyset$, hence $SB \cap C \neq \emptyset$ and so, by corollary 4.7, $\mathfrak{M}^C, C \Vdash B$. It follows that $\Gamma \not\models A$.

Right-to-left: Assume the right-hand-side of the theorem and take any model M and state s in M and suppose that $s \Vdash \Gamma$. We show $s \Vdash A$. For each $B \in \Gamma$, we have $s \Vdash B$ and so, by lemma 3.3, $s \Vdash \bigwedge x$ for some $x \in \mathcal{S}B$. So for some $X \in \mathcal{S}\Gamma$, we have $s \Vdash \bigwedge x$ for each $x \in X$: we now hold this X fixed. By assumption, for some $y \in \mathcal{S}A$ and some $x \in X$, we have $x \sqsubseteq y \sqsubseteq \bigcup X$. Moreover, $y - x \sqsubseteq z$ for some $z \in X$ and hence $s \Vdash \bigwedge z$. So for any $l \in y - x$, there is some $t \sqsubseteq s$ such that $t \Vdash l$. It follows that there is some $u \sqsubseteq s$ such that $u \Vdash \bigwedge(y - x)$, hence $s \sqcup u \Vdash \bigwedge x \wedge \bigwedge(y - x)$ and so $s \Vdash \bigwedge y$. Since $y \in \mathcal{S}A$, lemma 3.3 gives us $s \Vdash A$. It follows that $\Gamma \models A$. ■

5 Compactness and Decidability

We turn to compactness. Note that we cannot meaningfully express compactness in terms of satisfiability (i.e., by saying that any set of formulas is satisfiable iff all its finite subsets are) since, as we have already noted, any set of formulas is satisfiable in the truthmaking semantics. So we present our compactness result (theorem 5.2 below) in terms of entailment.

Lemma 5.1. *Let \top be a constant verified and falsified by every state in every model. For any formula A and set of sentence letters P , let $A[\top/P]$ be the formula obtained from A by uniformly substituting \top for each $p \in P$ in A . Then $A \models A[\top/P]$.*

Proof: By induction on A . The base case holds trivially, so suppose the result holds for all B less complex than A , suppose $s \Vdash A$, and consider these cases.

- $A := A_1 \wedge A_2$. Then $s = s_1 \sqcup s_2$ where $s_1 \Vdash A_1$ and $s_2 \Vdash A_2$. By hypothesis, $s_1 \Vdash A_1[\top/P]$ and $s_2 \Vdash A_2[\top/P]$, hence $s \Vdash A_1[\top/P] \wedge A_2[\top/P]$ and so $s \Vdash A[\top/P]$.
- $A := A_1 \vee A_2$. Then $s \Vdash A_1$, $s \Vdash A_2$, or else $s = s_1 \sqcup s_2$ where $s_1 \Vdash A_1$ and $s_2 \Vdash A_2$. If $s \Vdash A_1$ then by hypothesis $s \Vdash A_2[\top/P]$, hence $s \Vdash A_1[\top/P] \vee A_2[\top/P]$ and so $s \Vdash (A_1 \vee A_2)[\top/P]$. Similarly if $s \Vdash A_2$. Otherwise, by hypothesis $s_1 \Vdash A_1[\top/P]$ and $s_2 \Vdash A_2[\top/P]$, hence $s \Vdash A_1[\top/P] \vee A_2[\top/P]$ and so $s \Vdash A[\top/P]$.
- Again, the cases for $A := \neg(A \vee B)$ and $A := \neg(A \wedge B)$ are similar to the cases above, respectively, and the case for $A := \neg\neg A$ is trivial. ■

Theorem 5.2 (Compactness). *If $\Gamma \models A$ then $\Delta \models A$ for some finite $\Delta \subseteq \Gamma$.*

Proof: Fix the conclusion A , and for any formula B , let B^A be the result of substituting \top in B for any sentence letter not in A . Let $\Gamma^A = \{B^A \mid B \in \Gamma\}$. Since \models is closed under uniform substitution, $\Gamma^A \models A$. We then partition Γ^A into equivalence classes and pick one sentence from each class: let the resulting set be Δ^A . Then $\Delta^A \models A$ too. And since Γ^A is constructed from a finite set of sentence letters, there are finitely many such equivalence classes and so Δ^A is finite. Now, for each $B^A \in \Delta^A$, we pick a corresponding $B' \in \Gamma$, such that $B'^A = B^A$. (Note that

B^A need not uniquely determine this B' .) Let Δ be the set of the chosen B' 's. Then $\Delta \subseteq \Gamma$ is finite. Now suppose $s \Vdash \Delta$. Then, by lemma 5.1, $s \Vdash \Delta^A$, hence $s \Vdash \Gamma^A$ and so $s \Vdash A$. It follows that $\Delta \models A$. ■

Theorem 5.3 (Decidability). *For finite Γ , it is decidable whether $\Gamma \models A$.*

Proof: By theorem 4.8, there is a correct algorithm for checking whether $\Gamma \models A$ which cycles through each $X \in \mathcal{S}\Gamma$, checking whether there is some $x \in X$ and some $y \in \mathcal{S}A$ such that $x \sqsubseteq y \sqsubseteq \bigcup X$. Each such x, y and $\bigcup X$ is a finite set, so each such check is a finite procedure. Since there are at most $|\mathcal{S}\Gamma| \cdot \max\{|X| \mid X \in \mathcal{S}\Gamma\} \cdot |\mathcal{S}A|$ such checks to perform, the procedure will terminate after finitely many steps. ■

6 Non-Vacuous and Convex Models

In this section, we consider two conditions in turn, *non-vacuity* and *convexity*, and investigate whether they affect the exact entailment relation.

Non-Vacuous Models

In *non-vacuous* models, every sentence letter p has a truthmaker and a falsemaker:

Definition 11 (Non-vacuous models). A model $M = \langle S, \sqsubseteq, |\cdot|^+, |\cdot|^- \rangle$ is *non-vacuous* iff, for each sentence letter p in the language, both $|p|^+$ and $|p|^-$ are nonempty.

In a non-vacuous model M , the sets $|A|^+$ and $|A|^-$ are non-empty for arbitrary formulas A (as the reader can easily check).

Definition 12 (Non-vacuous exact entailment). Γ *non-vacuously exactly entails* A , $\Gamma \models_{nv} A$, just in case for each non-vacuous model M and state s in M : $M, s \Vdash A$ whenever $M, s \Vdash \Gamma$.

We show that non-vacuous exact entailment is exact entailment:

Theorem 6.1. $\Gamma \models_{nv} A$ if and only if $\Gamma \models A$.

Proof, left-to-right: By contraposition. Suppose $\Gamma \not\models A$. Then there is a model M and state s in M such that $M, s \Vdash \Gamma$ but $M, s \not\Vdash A$. We transform M into M^* by adding a single state, t , such that $u \sqsubseteq t$ for each state u in M , and adding t to both $|p|^+$ and $|p|^-$ for every sentence letter p . Then $t \sqcup u = t$ for each state u in M^* , hence each pair of states in M^* has a least upper bound. This guarantees that M^* is a genuine model. Moreover, M^* is non-vacuous, since $t \in |p|^+ \cap |p|^-$ for each p . Now we show, by induction on A , that $M^*, u \Vdash A$ iff $M, u \Vdash A$ for each u in M .

In the *only if* direction, the base case holds, given that t is not in M . So suppose the result holds for all B less complex than A , and consider these cases.

- $A := A_1 \wedge A_2$. Then $u = u_1 \sqcup u_2$ where $M^*, u_1 \Vdash A_1$ and $M^*, u_2 \Vdash A_2$. So by hypothesis, $M, u_1 \Vdash A_1$ and $M, u_2 \Vdash A_2$, hence $M, u \Vdash A$.
- $A := A_1 \vee A_2$. Then $M^*, s \Vdash A_1$, $M^*, s \Vdash A_2$, or $u = u_1 \sqcup u_2$ where $M^*, u_1 \Vdash A_1$ and $M^*, u_2 \Vdash A_2$. So by hypothesis, $M, u \Vdash A_1$, $M, u \Vdash A_2$, or else $M, u_1 \Vdash A_1$ and $M, u_2 \Vdash A_2$. Either way, we have $M, u \Vdash A$.
- The $A := \neg(A_1 \vee A_2)$ and $A := \neg(A_1 \wedge A_2)$ cases are similar, and the $A := \neg\neg A_1$ case is trivial.

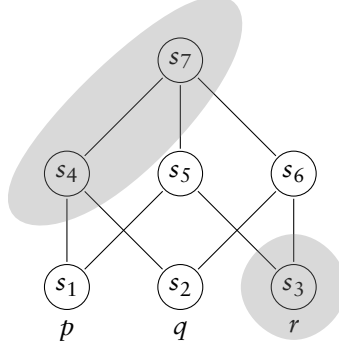
The *if* direction is similar. So, given that $M, s \Vdash \Gamma$ but $M, s \not\Vdash A$, we have $M^*, s \Vdash \Gamma$ and $M^*, s \not\Vdash A$, and hence $\Gamma \not\#_{mv} A$.

Right-to-left: Trivial, given that all non-vacuous models are models. ■

It is worth noting that the proof of theorem 4.8 gives us an alternative proof of theorem 6.1, given that the congruent canonical model used in that proof is non-vacuous.

Convex Models

Our current understanding of truthmaking allows structures like the following, where the shaded area marks truthmakers for $(p \wedge q) \vee r$:



Here, s_7 has parts (s_5 and s_6) which do not truthmake $(p \wedge q) \vee r$, each of which has a further part (s_3) which does truthmake $(p \wedge q) \vee r$. So, we can begin with a truthmaker for $(p \wedge q) \vee r$, add to it so that it will no longer truthmake $(p \wedge q) \vee r$, and add to it further, so that it will again truthmake $(p \wedge q) \vee r$. In other words, the set of states $|(p \wedge q) \vee r|^+$ is not *convex*.

We can work instead with the *convex closure* of the truthmaking and falsmaking sets (definition 7), which we denote $|A|_*^+$ and $|A|_*^-$. These obey a selection lemma:

Lemma 6.2 (Convex selection lemma). *For any formula A , model M and state s in M : $s \in |A|_*^+$ iff there are $x, y \in SA$ & states $t \sqsubseteq s \sqsubseteq u$ such that $t \Vdash \wedge x$ & $u \Vdash \wedge y$.*

Proof, left-to-right: Assume $s \in |A|_*^+$. Then by definition there are $t, u \in |A|^+$ with $t \sqsubseteq s \sqsubseteq u$. Since $t \Vdash A$ and $u \Vdash A$, by lemma 3.3 there are $x, y \in \mathcal{S}A$ such that $t \Vdash \wedge x$ and $u \Vdash \wedge y$.

Right-to-left: Assume there are $x, y \in \mathcal{S}A$ and states $t \sqsubseteq s \sqsubseteq u$ such that $t \Vdash \wedge x$ and $u \Vdash \wedge y$. By lemma 3.3, $t \Vdash A$ and $u \Vdash A$ and so, by definition, $s \in |A|_*^+$. ■

We use these notions to define *convex exact entailment*, and show that it coincides with exact entailment:

Definition 13 (Convex exact entailment). Γ *convex exactly entails* A , $\Gamma \vDash_* A$, iff for any model M : $|A|_*^+ \subseteq |\Gamma|_*^+$ in M .

Theorem 6.3 (Convex exact entailment). $\Gamma \vDash_* A$ iff $\Gamma \vDash A$.

Proof, left-to-right: Suppose $\Gamma \not\vDash A$. Then there is a model $M = \langle S, \sqsubseteq, |\cdot|^+, |\cdot|^- \rangle$ and state s in M such that $M, s \Vdash \Gamma$ but $M, s \not\vDash A$. Let M^s be the model just like M except restricted to states $u \sqsubseteq s$. Then, for all $u \sqsubseteq s$ in M , $M^s, u \Vdash A$ iff $M, u \Vdash A$. Hence $M^s, s \Vdash \Gamma$ but $M^s, s \not\vDash A$, so $s \notin |A|_*^+$ and so (since s is the top state in M^s) $s \notin |A|_*^+$. Since $|\Gamma|_*^+ \subseteq |A|_*^+$, $\Gamma \not\vDash_* A$.

Right-to-left: Suppose $\Gamma \vDash A$ and $s \in |\Gamma|_*^+$. Then, for each $B \in \Gamma$, there are states $s_1^B \sqsubseteq s \sqsubseteq s_2^B$ such that $s_1^B \Vdash B$ and $s_2^B \Vdash B$. By lemma 3.3, for each $B \in \Gamma$, there are selections $x_1^B, x_2^B \in \mathcal{S}B$ such that $s_1^B \Vdash \wedge x_1^B$ and $s_2^B \Vdash \wedge x_2^B$. Let $X_1 = \{x_1^B \mid B \in \Gamma\}$ and $X_2 = \{x_2^B \mid B \in \Gamma\}$. Then $X_1, X_2 \in \mathcal{S}\Gamma$. So by theorem 4.8, there are $y_1, y_2 \in \mathcal{S}A$, $z_1 \in X_1$, and $z_2 \in X_2$ such that $z_1 \sqsubseteq y_1 \sqsubseteq \cup X_1$ and $z_2 \sqsubseteq y_2 \sqsubseteq \cup X_2$. For some $B', B'' \in \Gamma$, $z_1 = x_1^{B'}$ and $z_2 = x_2^{B''}$ and hence $s_1^{B'} \Vdash \wedge z_1$ and $s_2^{B''} \Vdash \wedge z_2$.

Now take any literal $l \in \cup X_1$. Then $l \in x_i^B$ for some $B \in \Gamma$ and $x_i \in \mathcal{S}B$. So there is a state $s^B \sqsubseteq s$ such that $s^B \Vdash \wedge x_i^B$ and, since x_i^B is finite, there is a state $s' \sqsubseteq s^B \sqsubseteq s$ such that $s' \Vdash l$. Now consider $y_1 - z_1$. This is a finite set of literals $\{l_1, \dots, l_n\} \subseteq X_1$ for which, by the preceding reasoning, there are states $t_i \sqsubseteq s$ such that $t_i \Vdash l_i$ for each $i \leq n$, and hence there is a state $t = (t_1 \sqcup \dots \sqcup t_n) \sqsubseteq s$ such that $t \Vdash \wedge (y_1 - z_1)$. Similarly, there is some $u \sqsubseteq s$ such that $u \Vdash \wedge (y_2 - z_2)$. Then $s_1^{B'} \sqcup t \Vdash \wedge y_1$ and $s_2^{B''} \sqcup u \Vdash \wedge y_2$. But $s_1^{B'} \sqsubseteq s \sqsubseteq s_2^{B''}$ and so $(s_1^{B'} \sqcup t) \sqsubseteq s \sqsubseteq (s_2^{B''} \sqcup u)$. By lemma 3.3, $s_1^{B'} \sqcup t \Vdash A$ and $s_2^{B''} \sqcup u \Vdash A$, and so $s \in |A|_*^+$. Hence $\Gamma \vDash_* A$. ■

An Alternative Approach to Convexity

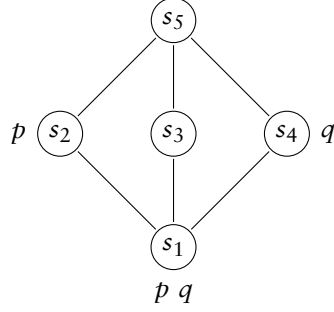
In defining \vDash_* , we have not changed our truthmaking or falsmaking clauses. There is an alternative approach, in which we replace these with truthmaking and falsmaking relations \Vdash_{cvx} and $\dashv\vdash_{cvx}$, defined recursively:

Definition 14.

$s \Vdash_{cvx} A \vee B$ iff either $s \Vdash_{cvx} A$; or $s \Vdash_{cvx} B$; or there are t, u such that:
 $t \Vdash_{cvx} A, u \Vdash_{cvx} B$ and either $t \sqsubseteq s \sqsubseteq t \sqcup u$ or $u \sqsubseteq s \sqsubseteq t \sqcup u$
 $s \dashv\vdash_{cvx} A \wedge B$ iff either $s \dashv\vdash_{cvx} A$; or $s \dashv\vdash_{cvx} B$; or there are t, u such that:
 $t \dashv\vdash_{cvx} A, u \dashv\vdash_{cvx} B$ and either $t \sqsubseteq s \sqsubseteq t \sqcup u$ or $u \sqsubseteq s \sqsubseteq t \sqcup u$

The remaining \Vdash_{conv} and $\dashv\!\!\dashv_{conv}$ clauses are identical to the \Vdash and $\dashv\!\!\dashv$ clauses given in definition 3, §2.

In general, these are not convex relations. In the model below, $s_1 \Vdash_{conv} p \wedge q$, $s_5 \Vdash_{conv} p \wedge q$, $s_1 \sqsubseteq s_3 \sqsubseteq s_5$, and yet $s_3 \not\Vdash_{conv} p \wedge q$:



This model is *non-distributive*, for $s_3 \sqcap (s_2 \sqcup s_4) = s_3 \neq s_1 = (s_3 \sqcap s_2) \sqcup (s_3 \sqcap s_4)$. And in general, we can show that any counter-model to convexity is non-distributive. Restricting to distributive models, the truthmaking and falsmaking sets defined over \Vdash_{conv} and $\dashv\!\!\dashv_{conv}$ are convex, and provide us with an alternative definition of convex exact entailment.

Definition 15 (Distributive models). A model $M = \langle S, \sqsubseteq, |\cdot|^+, |\cdot|^- \rangle$ is *distributive* iff, for all $s, t, u \in S$: $s \sqcap (t \sqcup u) = (s \sqcap t) \sqcup (s \sqcap u)$.

Definition 16. $\Gamma \models_{conv} A$ iff for every distributive model M in which $|p|^+$ and $|p|^-$ are convex for every sentence letter p , and for every state s in M : $M, s \Vdash_{conv} A$ only if $M, s \dashv\!\!\dashv_{conv} \Gamma$.

Lemma 6.4 (Convexity). *In a distributive model M for which $|p|^+$ and $|p|^-$ are convex for every sentence letter p , $\{s \mid s \Vdash_{conv} A\} = |A|_*^+$ and $\{s \mid s \dashv\!\!\dashv_{conv} A\} = |A|_*^-$ for every A .*

Proof: The proof, which we omit here, shows that $\{s \mid s \Vdash_{conv} A\} \subseteq |A|_*^+$ and that $|A|_*^+ \subseteq \{s \mid s \Vdash_{conv} A\}$ by induction on A . We note that the only case to make use of distribution is the conjunction case for $|A|_*^+ \subseteq \{s \mid s \Vdash_{conv} A\}$. ■

Corollary 6.5. *In a distributive model in which $|p|^+$ and $|p|^-$ are convex for every sentence letter p , if $s \Vdash_{conv} A$, $u \dashv\!\!\dashv_{conv} A$, and $s \sqsubseteq t \sqsubseteq u$, then $t \Vdash_{conv} A$.*

Proof: Immediate from lemma 6.4. ■

Theorem 6.6. $\Gamma \models_{conv} A$ iff $\Gamma \models_* A$ iff $\Gamma \models A$.

Proof: Immediate from lemma 6.4 and theorem 6.3. ■

7 Non-Vacuous Convex Models

We have seen that both non-vacuous exact entailment and convex exact entailment coincide with exact entailment. But when we combine both conditions, non-vacuity and convexity, we obtain a different consequence relation, which we investigate in this section.

Definition 17 (Non-vacuous convex exact entailment). Γ *non-vacuously convex entails* A , $\Gamma \models_{nv^*} A$, just in case, for every non-vacuous model $M: |A|_*^+ \subseteq |\Gamma|_*^+$ in M .

We showed above that \models coincides with both \models_{nv} and \models_* . However, it does not coincide with \models_{nv^*} . Non-vacuous convex entailment supports inferences

$$\bigwedge x \models_{nv^*} \bigwedge x_1 \vee \bigwedge x_2$$

for any sets of literals x, x_1, x_2 such that $x_1 \subseteq x \subseteq x_2$ (whereas exact entailment need not support such inferences). For example, we have

$$p \vee (p \wedge q) \vee (p \wedge q \wedge r) \models_{nv^*} p \vee (p \wedge q \wedge r)$$

and yet, as the reader can easily check,

$$p \vee (p \wedge q) \vee (p \wedge q \wedge r) \not\models p \vee (p \wedge q \wedge r)$$

We now prepare for a syntactic characterisation of non-vacuous convex entailment, along the lines of theorem 4.8.

Lemma 7.1 (Congruent canonical model convexity). *For any set of sets of literals $C \subseteq 2^\Lambda$, let \mathfrak{M}^C be the congruent canonical model over C . Then, for any sets of literals x, y and states $\mathfrak{s} \neq C, \mathfrak{t}$, and \mathfrak{u} in \mathfrak{M}^C : if $\mathfrak{s} \subseteq \mathfrak{t} \subseteq \mathfrak{u}$, $\mathfrak{s} \Vdash \bigwedge x$, and $\mathfrak{u} \Vdash \bigwedge z$, then there is some y such that $x \subseteq y \subseteq z$ and $\mathfrak{t} \Vdash \bigwedge y$.*

Proof: Assume $\mathfrak{s} \subseteq \mathfrak{t} \subseteq \mathfrak{u}$, $\mathfrak{s} \Vdash \bigwedge x$, and $\mathfrak{u} \Vdash \bigwedge z$ in \mathfrak{M}^C . Then by construction of \mathfrak{M}^C , $\mathfrak{s} = [x]_C$ and $\mathfrak{u} = [z]_C$ and, for some y , $\mathfrak{t} = [y]_C$. By definition, $[z]_C = [y]_C \sqcup^C [z]_C = [y \cup z]_C$, so $z \equiv_C y \cup z$, so by lemma 4.2, $z \approx_C y \cup z$. Then by definition, either (i) $z = y \cup z$ (so $y \subseteq z$) or else (ii) there are $c_1, c_2 \in C$ such that $c_1 \subseteq z$, $c_2 \subseteq (y \cup z)$, and $z - \cup C = (y \cup z) - \cup C$. So, if $y \not\subseteq z$, then $y \in C$ and $z \cap \cup C \neq \emptyset$. Either way, there is some $y' \in [y]_C$ such that $y' \subseteq z$. Since $[y']_C = [y]_C$, we have $[x]_C \subseteq [y']_C$. By the same reasoning, if $x \not\subseteq y$, then $x \in C$ and $y \cap \cup C \neq \emptyset$. But by assumption, $[x]_C \neq C$, hence $x \notin C$, hence $x \subseteq y' \subseteq z$. Finally, by lemma 4.6, $[y]_C \Vdash \bigwedge y'$ and hence $\mathfrak{t} \Vdash \bigwedge y'$. ■

Our previous characterisation theorem (4.8) for \models fails for \models_{nv^*} , for it requires (in the case of single-premise inferences, $A \models B$) that every selection from A to be a selection from B too. But non-vacuous convex exact entailment relaxes this requirement: each selection from the premise must be in-between (wrt \subseteq) selections from the conclusion. This suggests that we should characterise $\Gamma \models_{nv^*} A$ in terms of the convex closure of $\mathcal{S}A$, \mathcal{S}_*A , in place of $\mathcal{S}A$. Theorem 7.2 below generalises this idea to the multiple-premise case. (Note that 4.8 is a special case of 7.2, for which $y \in \mathcal{S}A$.)

Definition 18. For any A , \mathcal{S}_*A is the convex closure (wrt \sqsubseteq) of $\mathcal{S}A$: the smallest set of sets of literals such that $y \in \mathcal{S}_*A$ whenever there are $x, z \in \mathcal{S}_*A$ such that $x \sqsubseteq y \sqsubseteq z$.

Theorem 7.2 (Characterisation of \models_{nv^*}). $\Gamma \models_{nv^*} A$ if and only if, for any $X \in \mathcal{S}\Gamma$, some $x \in X$ and some $y \in \mathcal{S}_*A$: $x \sqsubseteq y \sqsubseteq \cup X$.

Proof, left-to-right: Assume that, for some $X \in \mathcal{S}_*\Gamma$ (which we keep fixed) and any $y \in \mathcal{S}_*A$, there is no $x \in X$ such that $x \sqsubseteq y \sqsubseteq \cup X$. Let C be the \sqcup , $-$, and convex closure of X , and \mathfrak{M}^C be the congruent canonical model over C . Following the proof of theorem 4.8, for any $y \in \mathcal{S}_*A$, there is no $s \in C$ such that $y \equiv_C s$, hence $\mathfrak{M}^C, C \not\models \wedge y$. Now suppose, for reductio, that $C \in |A|_*^+$. Then, by lemma 6.2, there are selections $y_1, y_2 \in \mathcal{S}A$ and states $s \sqsubseteq C \sqsubseteq \mathbf{u}$ in \mathfrak{M}^C such that $s \in |\wedge y_1|_*^+$ and $\mathbf{u} \in |\wedge y_2|_*^+$. Then $\mathfrak{M}^C, s \models \wedge y_1$ and $\mathfrak{M}^C, \mathbf{u} \models \wedge y_2$. Given the reasoning above, $s \neq C \neq \mathbf{u}$ and so, by lemma 7.1, there is a y such that $y_1 \sqsubseteq y \sqsubseteq y_2$ and $\mathfrak{M}^C, C \models \wedge y$. But, since $y_1, y_2 \in \mathcal{S}A$, it follows that $y \in \mathcal{S}_*A$: contradiction. So $C \notin |A|_*^+$. Moreover (by the proof of theorem 4.8), $C \in |\Gamma|^+$, hence $C \in |\Gamma|_*^+$. Since \mathfrak{M}^C is non-vacuous, we have $\Gamma \not\models_{nv^*} A$.

Right-to-left: Assume the right-hand-side of the theorem and take any non-vacuous model M and state s such that $s \in |\Gamma|_*^+$. By lemma 6.2, for each $B \in \Gamma$, there are $x, y \in \mathcal{S}A$ and states $t \sqsubseteq s$ and $u \sqsupseteq s$ such that $t \models \wedge x$ and $u \models \wedge y$. Then there are $X_1, X_2 \in \mathcal{S}\Gamma$ (which we hold fixed) such that, for each $x_1 \in X_1$, there is a $t \sqsubseteq s$ such that $t \models \wedge x_1$ and, for each $x_2 \in X_2$, there is a $u \sqsupseteq s$ such that $s \models \wedge x_2$. By assumption, there are $x_1 \in X_1$ and $y_1 \in \mathcal{S}A$ with $x_1 \sqsubseteq y_1 \sqsubseteq \cup X_1$. So, for some $t \sqsubseteq s$, $t \models \wedge x_1$. Now let $y - x = \{l_1, \dots, l_n\}$. For each such l_i , there is a $t_i \sqsubseteq s$ such that $t_i \models l_i$, hence $t \sqcup t_1 \sqcup \dots \sqcup t_n \models \wedge y$ and $t \sqcup t_1 \sqcup \dots \sqcup t_n \sqsubseteq s$. Similarly, there are $x_2 \in X_2$ and $y_2 \in \mathcal{S}A$ with $x_2 \sqsubseteq y_2 \sqsubseteq \cup X_2$. So, for some $u \sqsupseteq s$, $u \models \wedge x_2$. Since M is non-vacuous, there is a v in M such that $v \models \wedge (y_2 - x_2)$, hence $x_2 \sqcup v \models \wedge y_2$, and $s \sqsubseteq (x_2 \sqcup v)$. Then lemma 6.2 implies $s \in |A|_*^+$, and hence $\Gamma \models_{nv^*} A$. ■

8 Proof Theory

In this section, we set out a proof system corresponding to exact entailment. (We leave a system corresponding to non-vacuous convex exact entailment for future work.) Our proof system defines a derivability relation \vdash , holding between a set of sets of formulas and a set of formulas. To avoid an over-abundance of ‘{’s and ‘}’s, we use an alternative notation for writing sequents, as follows:

$$A_1, \dots, A_n; B_1, \dots, B_m; C_1, \dots, C_k \vdash D_1, \dots, D_i$$

Here, we have two premise-grouping pieces of punctuation, ‘;’ and ‘,’. A list ‘ A_1, \dots, A_n ’ not broken by a semicolon notates a set of formulas, whereas the concatenation of sets of formulas is notated by the semicolon. So, for example, ‘ $A; B; C$ ’ notates the set $\{\{A\}, \{B\}, \{C\}\}$, whereas ‘ A, B, C ’ notates $\{\{A, B, C\}\}$. Observe that, in this notation, ‘ $C; B; A$ ’ and ‘ $C; C; B; A$ ’ also notate the former

set, and ‘ C, B, A ’ and ‘ C, C, B, A ’ also notate the latter. (Which set a list notates is not affected by re-ordering or repetition.)

The intuitive interpretation of this notation is that comma-separated formulas are taken conjunctively, whereas semicolon-separated formulas are taken individually. So, the above sequent

$$A_1, \dots, A_n; B_1, \dots, B_m; C_1, \dots, C_k \vdash D_1, \dots, D_i$$

is intended to capture the inference from premises $A_1 \wedge \dots \wedge A_n$, $B_1 \wedge \dots \wedge B_m$, and $C_1 \wedge \dots \wedge C_k$, to conclusion $D_1 \wedge \dots \wedge D_i$. Note that this is not the usual multi-conclusion sequent, since ‘ D_1, \dots, D_i ’ on the right captures the D s conjunctively, not individually.

To preserve the appearance of traditional sequent rules, we will henceforth use upper-case ‘ Γ ’, ‘ Δ ’ as variables for sets of sets of formulas, and use lower-case ‘ γ ’, ‘ δ ’, ‘ ξ ’ as variables for sets of formulas. We then write the general form of a sequent as ‘ $\Gamma \vdash \gamma$ ’. We indicate that A and B (together with the formulas in γ) are to be taken conjunctively on the left (or the right) by writing ‘ $\Gamma; \gamma, A, B \vdash \delta$ ’ (or ‘ $\Gamma \vdash \gamma, A, B$ ’).

Structural Rules

$$\begin{array}{ccc} \frac{}{\Gamma \vdash \gamma} \text{ (ID)} & \frac{\Gamma \vdash \delta}{\Gamma; \gamma \vdash \delta} \text{ (WEAK)} & \frac{\Gamma \vdash \gamma \quad \Gamma; \gamma \vdash \delta}{\Gamma \vdash \delta} \text{ (CUT)} \\ \\ \frac{\Gamma; \gamma \vdash \xi \quad \Gamma; \delta \vdash \chi}{\Gamma; \gamma, \delta \vdash \xi, \chi} \text{ (,I)} & & \frac{\Gamma \vdash \gamma \quad \Gamma \vdash \delta, \xi}{\Gamma \vdash \gamma, \delta} \text{ (,2)} \end{array}$$

Since this notation for sets is invariant under reordering and repetition, the system automatically has the following left and right exchange and contraction rules, both for the comma (left and right) and the semicolon (on the left only) built in:

$$\begin{array}{ccc} \frac{\Gamma; \gamma, A, B, \delta \vdash \xi}{\Gamma; \gamma, B, A, \delta \vdash \xi} \text{ (EX,L)} & \frac{\Gamma \vdash \gamma, A, B, \delta}{\Gamma \vdash \gamma, B, A, \delta} \text{ (EX,R)} & \frac{\Gamma; \Delta_1; \Delta_2; \Xi \vdash \gamma}{\Gamma; \Delta_2; \Delta_1; \Xi \vdash \gamma} \text{ (EX;L)} \\ \\ \frac{\Gamma; \gamma, A, A, \delta \vdash \xi}{\Gamma; \gamma, A, \delta \vdash \xi} \text{ (W,L)} & \frac{\Gamma \vdash \gamma, A, A, \delta}{\Gamma \vdash \gamma, A, \delta} \text{ (W,R)} & \frac{\Gamma; \Delta; \Delta; \Xi \vdash \gamma}{\Gamma; \Delta; \Xi \vdash \gamma} \text{ (W;L)} \end{array}$$

Some comments on (,I) and (,2) are in order. (,I) allows premises to be combined with ‘;’ so long as the conclusions are simultaneously combined with ‘,’. Intuitively, (,I) says that, if we can prove B_1 from A_1 and B_2 from A_2 , then we can prove $B_1 \wedge B_2$ from $A_1 \wedge A_2$. (,2) allows us to combine a conclusion, γ , with any nonempty subset δ of a conclusion δ, ξ . The intuition here is that, if Γ exactly proves γ , and Γ is sufficient for δ (in the sense that Γ exactly proves some superset δ, ξ), then Γ exactly proves γ, δ .

These two rules (,I) and (,2) perform genuinely distinct duties. If we attempt to combine them into a single rule,

$$\frac{\Gamma; \gamma \vdash \zeta \quad \Gamma; \delta \vdash \chi, \sigma}{\Gamma; \gamma, \delta \vdash \zeta, \chi} (\times)$$

we will be able to prove too much, as the following derivation shows:

$$\frac{\frac{\frac{A \vdash A \quad A, B \vdash A, B}{A, B \vdash A, A} (\times)}{A, B \vdash A} (\text{w,R})}{A \wedge B \vdash A} (\wedge\text{L})$$

But $A \wedge B \neq A$, so (\times) is unsound.

Logical Rules

$$\begin{array}{cc} \frac{\Gamma; \gamma, A, B \vdash \delta}{\Gamma; \gamma, A \wedge B \vdash \delta} (\wedge\text{L}) & \frac{\Gamma \vdash \gamma, A, B}{\Gamma \vdash \gamma, A \wedge B} (\wedge\text{R}) \\ \frac{\Gamma; \gamma, \neg A, \neg B \vdash \delta}{\Gamma; \gamma, \neg(A \vee B) \vdash \delta} (\neg\vee\text{L}) & \frac{\Gamma \vdash \gamma, \neg A, \neg B}{\Gamma \vdash \gamma, \neg(A \vee B)} (\neg\vee\text{R}) \\ \frac{\Gamma; \gamma, A \vdash \zeta \quad \Gamma; \gamma, B \vdash \zeta}{\Gamma; \gamma, A \vee B \vdash \zeta} (\vee\text{L}) & \frac{\Gamma \vdash \gamma, A/B}{\Gamma \vdash \gamma, A \vee B} (\vee\text{R}) \\ \frac{\Gamma; \gamma, \neg A \vdash \zeta \quad \Gamma; \gamma, \neg B \vdash \zeta}{\Gamma; \gamma, \neg(A \wedge B) \vdash \zeta} (\neg\wedge\text{L}) & \frac{\Gamma \vdash \gamma, \neg A/\neg B}{\Gamma \vdash \gamma, \neg(A \wedge B)} (\neg\wedge\text{R}) \\ \frac{\Gamma; \gamma, A \vdash \delta}{\Gamma; \gamma, \neg\neg A \vdash \delta} (\neg\neg\text{L}) & \frac{\Gamma \vdash \gamma, A}{\Gamma \vdash \gamma, \neg\neg A} (\neg\neg\text{R}) \end{array}$$

A derivation of $\Gamma \vdash \gamma$ is a tree of rule instances, with an instance of (ID) at each leaf and $\Gamma \vdash \gamma$ at the root.

Examples

To illustrate the system, we offer some sample derivations. To derive conjunction introduction:

$$\frac{\frac{A \vdash A \quad B \vdash B}{A, B \vdash A, B} (\text{I})}{A, B \vdash A \wedge B} (\wedge\text{R})$$

To derive distribution of \wedge over \vee :

$$\begin{array}{c}
\frac{\frac{A \vdash A \quad B \vdash B}{A, B \vdash A, B} (\text{,I})}{A, B \vdash A \wedge B} (\wedge\text{R}) \quad \frac{\frac{A \vdash A \quad C \vdash C}{A, C \vdash A, C} (\text{,I})}{A, C \vdash A \wedge C} (\wedge\text{R}) \\
\frac{A, B \vdash (A \wedge B) \vee (A \wedge C)}{A, B \vdash (A \wedge B) \vee (A \wedge C)} (\vee\text{R}) \quad \frac{A, C \vdash (A \wedge B) \vee (A \wedge C)}{A, C \vdash (A \wedge B) \vee (A \wedge C)} (\vee\text{R}) \\
\frac{A, B \vee C \vdash (A \wedge B) \vee (A \wedge C)}{A \wedge (B \vee C) \vdash (A \wedge B) \vee (A \wedge C)} (\wedge\text{L})
\end{array}$$

To derive a disjunction from the corresponding conjunction:

$$\begin{array}{c}
\frac{A \vdash A}{A \vdash A \vee B} (\vee\text{R}) \quad \frac{B \vdash B}{B \vdash A \vee B} (\vee\text{R}) \\
\frac{A, B \vdash A \vee B, A \vee B}{A, B \vdash A \vee B} (\text{,I}) \\
\frac{A, B \vdash A \vee B}{A \wedge B \vdash A \vee B} (\wedge\text{L})
\end{array}$$

9 Soundness and Completeness

The proof system just presented is sound and complete with respect to exact truthmaking entailment. Let's introduce a bit more terminology to help us through these proofs.

Definition 19 (Fit and support). For any set of literals y and any set of sets of literals X , we will say that y *fits* X iff there is some $x \in X$ such that $x \subseteq y \subseteq \cup X$. For any set of formulas Γ and formula A , we say that Γ *supports* A iff, for any $X \in \mathcal{S}\Gamma$, some $y \in \mathcal{S}A$ fits X .

The idea here is that y 's fitting X corresponds to $X \vdash y$ (as we show in lemma 9.2 below). We found we were unable to establish soundness in the usual way, via a semantic argument. The proof below goes via characterisation theorem 4.8 from §4.

Theorem 9.1 (Soundness). *For any $\Gamma \subseteq 2^{\mathcal{L}}$, let $\Gamma^\wedge = \{\wedge \gamma \mid \gamma \in \Gamma\}$. Then $\Gamma \vdash \gamma$ only if $\Gamma^\wedge \models \wedge \gamma$.*

Proof: Given the characterisation theorem 4.8, it is sufficient to show that Γ^\wedge supports $\wedge \gamma$ whenever $\Gamma \vdash \gamma$. Since this holds trivially for (ID) ($\{A\}$ supports A), it is sufficient to show that each rule preserves the support relation from upper to lower sequents. We show the cases for our structural rules (,I) and (,2), and for a sample logical rule, (vL). The other structural rules are straightforward, and the cases for the other logical rules are similar to the (vL) case.

(,I) Suppose $(\Gamma \cup \{\gamma\})^\wedge$ supports $\wedge \xi$ and $(\Gamma \cup \{\delta\})^\wedge$ supports $\wedge \chi$. Now consider any $X \in \mathcal{S}((\Gamma \cup \{\gamma \cup \delta\})^\wedge) = \mathcal{S}(\Gamma^\wedge \cup \{\wedge(\gamma \cup \delta)\})$. Then $X = X_1 \cup \{x\}$ where $X_1 \in \mathcal{S}\Gamma^\wedge$ and $x \in \mathcal{S}\wedge(\gamma \cup \delta)$, hence $x = x_1 \cup x_2$, where $x_1 \in \mathcal{S}\wedge \gamma$ and $x_2 \in \mathcal{S}\wedge \delta$. Then $X_1 \cup \{x_1\} \in \mathcal{S}((\Gamma \cup \{\gamma\})^\wedge)$ and so, by assumption, some $y \in \mathcal{S}\wedge \xi$ fits $X_1 \cup \{x_1\}$. Similarly, $X_1 \cup \{x_2\} \in \mathcal{S}((\Gamma \cup \{\delta\})^\wedge)$ and so, by assumption, some $z \in \mathcal{S}\wedge \chi$ fits $X_1 \cup \{x_2\}$. Then there are $u \in X_1 \cup \{x_1\}$ and $v \in X_1 \cup \{x_2\}$ such that $u \subseteq y$ and $v \subseteq z$. If $u \in X_1$ or $v \in X_1$, then either $u \in X$ or $v \in X$.

If not, then $u = x_1$, $v = x_2$, so $u \cup v \in X$. Either way, we have some $w \in X$ with $w \subseteq y \cup v$. Moreover, $y \subseteq \cup X_1 \cup \{x_1\}$ and $z \subseteq \cup X_1 \cup \{x_2\}$, and so $y \cup z \subseteq \cup(X_1 \cup \{x_1\} \cup \{x_2\}) = \cup X$. So $y \cup z$ fits X . Since $y \cup z \in \mathcal{S} \wedge (\xi \cup \chi)$, it follows that $(\Gamma \cup \{\gamma \cup \delta\})^\wedge$ supports $\wedge(\xi \cup \chi)$.

(,2) Suppose Γ^\wedge supports both $\wedge \gamma$ and $\wedge(\delta \cup \xi)$. Now consider any $X \in \mathcal{S}\Gamma^\wedge$. By assumption, some $y \in \mathcal{S} \wedge \gamma$ and some $z \in \mathcal{S} \wedge (\delta \cup \xi)$ each fit X . Then $z = z_1 \cup z_2$ where $z_1 \in \mathcal{S} \wedge \delta$ and $z_2 \in \wedge \xi$, hence $y \cup z_1 \in \mathcal{S} \wedge (\gamma \cup \delta)$. So there is an $x \in X$ such that $x \subseteq y$, hence $x \subseteq y \cup z_1$. Moreover, $y \subseteq \cup X$ and $z_1 \subseteq z \subseteq \cup X$, hence $y \cup z_1 \subseteq \cup X$. It follows that $y \cup z_1$ fits X , and hence that Γ^\wedge supports $\wedge(\gamma \cup \delta)$.

(vL) Suppose $(\Gamma \cup \{\gamma \cup \{A\}\})^\wedge = \Gamma^\wedge \cup \{\wedge \gamma \wedge A\}$ and $(\Gamma \cup \{\gamma \cup \{B\}\})^\wedge = \Gamma^\wedge \cup \{\wedge \gamma \wedge B\}$ each support $\wedge \xi$, and consider any

$$X \in \mathcal{S}((\Gamma \cup \{\gamma \cup \{A \vee B\}\})^\wedge) = \mathcal{S}(\Gamma^\wedge \cup \{\wedge \gamma \wedge (A \vee B)\}).$$

Then $X = X_1 \cup \{x_2 \cup x_3\}$ where $X_1 \in \mathcal{S}\Gamma^\wedge$, $x_2 \in \mathcal{S} \wedge \gamma$, and $x_3 \in \mathcal{S}(A \vee B)$. Then (i) $x_3 \in \mathcal{S}A$, (ii) $x_3 \in \mathcal{S}B$, or (iii) $x_3 = z_1 \cup z_2$ where $z_1 \in \mathcal{S}A$ and $z_2 \in \mathcal{S}B$. If (i) then by assumption, some $y \in \mathcal{S} \wedge \xi$ fits $X_1 \cup \{x_2 \cup x_3\}$ and hence y fits X . Similarly if (ii). If (iii), then some $y \in \mathcal{S} \wedge \xi$ fits $X_1 \cup \{x_2 \cup z_1\}$ and, since $X_1 \subseteq X$ and $x_2 \cup z_1 \subseteq x_2 \cup x_3 \in X$, y also fits X . It follows that $(\Gamma \cup \{\gamma \cup \{A \vee B\}\})^\wedge$ supports $\wedge \xi$. ■

Now we build up to a completeness proof, by establishing the following lemmas.

Lemma 9.2. *If y fits X , then $X \vdash y$.*

Proof: Suppose y fits X . Then by definition, there is some $x \in X$ such that $x \subseteq y \subseteq \cup X$ and so, via (ID) and (WEAK), $X \vdash x$. Now let $y - x = \{l_1, \dots, l_n\}$. For each l_i , $i \leq n$, there is some $z \in X$ such that $l_i \in z$, hence $X \vdash z$. So by n applications of (,2), we get $X \vdash x, l_1, \dots, l_n$, which is $X \vdash y$. ■

Lemma 9.3. *If $y \in \mathcal{S}A$ and y fits X , then $X \vdash A$.*

Proof: By induction on A . For the base case, we have $y = \{A\}$ and so, by lemma 9.2, $X \vdash y$ and hence $X \vdash \{A\}$, which we conventionally write as $X \vdash A$. Now assume the result holds for all B less complex than A , and consider these cases.

- $A := A_1 \wedge A_2$. Then $y = y_1 \cup y_2$ where $y_1 \in \mathcal{S}A_1$ and $y_2 \in \mathcal{S}A_2$ and, for some $x \in X$, we have $x \subseteq (y_1 \cup y_2) \subseteq \cup X$. Now let $Y = X - x$, $x_1 = x \cap y_1$ and $x_2 = x \cap y_2$. Then y_1 fits $Y \cup \{x_1\}$ and y_2 fits $Y \cup \{x_2\}$. So by hypothesis, $Y; x_1 \vdash A_1$ and $Y; x_2 \vdash A_2$. Applying (,I) and (\wedge R), we derive $Y; x_1, x_2 \vdash A_1, A_2$ and then $Y; x_1, x_2 \vdash A_1 \wedge A_2$. Here, ' $Y; x_1, x_2$ ' notates the set

$$Y \cup \{x_1 \cup x_2\} = Y \cup \{(x \cap y_1) \cup (x \cap y_2)\} = Y \cup \{x\} = X$$

since $x \subseteq (y_1 \cup y_2)$, and hence $X \vdash A$.

- $A := A_1 \vee A_2$. Then either $y \in \mathcal{S}A_1$, $y \in \mathcal{S}A_2$, or else $y = y_1 \cup y_2$ where $y_1 \in \mathcal{S}A_1$ and $y_2 \in \mathcal{S}A_2$. If $y \in \mathcal{S}A_1$ then, by hypothesis, $X \vdash A_1$, and by $(\vee R)$, we infer $X \vdash A$. Similarly, if $y \in \mathcal{S}A_2$ then $X \vdash A_2$ and hence $X \vdash A$. Otherwise, reasoning as in the \wedge case, we infer $X \vdash A_1, A_2$. Then using $(\vee R)$, we infer $X \vdash A_1 \vee A_2, A_1 \vee A_2$, which (given that contraction is built into our notation) amounts to $X \vdash A$.
- The $A := \neg(A_1 \vee A_2)$ and $A := \neg(A_1 \wedge A_2)$ cases are similar to the cases above (respectively), and the $A := \neg\neg A_1$ case is trivial. ■

Lemma 9.4. *For any $\Gamma \subseteq 2^{\mathcal{L}}$, $\gamma \subseteq \mathcal{L}$, A and B : if $\Gamma; \gamma, \beta \vdash A$ for each $\beta \in \mathcal{S}B$, then $\Gamma; \gamma, B \vdash A$.*

Proof: By induction on the complexity of B . Assume $\Gamma; \gamma, \beta \vdash A$ for each $\beta \in \mathcal{S}B$. For the base case $B := p$ or $B := \neg p$, we have $\mathcal{S}B = \{\{p\}\}$ or $\mathcal{S}B = \{\{\neg p\}\}$, so the result is immediate. For our inductive hypothesis, assume that for all C less complex than B , if $\Gamma; \gamma, \beta \vdash A$ for each $\beta \in \mathcal{S}C$, then $\Delta; \gamma, C \vdash A$. Now consider these cases.

- $B := B_1 \wedge B_2$. Then for each $\delta \in \mathcal{S}B$, $\delta = \delta_1 \cup \delta_2$, where $\delta_i \in \mathcal{S}B_i$. So by assumption, $\Gamma; \gamma, \beta_1, \beta_2 \vdash A$ for each $\beta_i \in \mathcal{S}B_i$ (since γ, β_1, β_2 denotes the set $\gamma \cup \beta_1 \cup \beta_2$). So by hypothesis, $\Gamma; \gamma, \beta_1, B_2 \vdash A$ for each $\beta_1 \in \mathcal{S}B_1$, and so again by hypothesis, $\Gamma; \gamma, B_1, B_2 \vdash A$. Then by $(\wedge L)$, $\Gamma; \gamma, B_1 \wedge B_2 \vdash A$.
- $B := B_1 \vee B_2$. Then $\mathcal{S}B_1 \subseteq \mathcal{S}B$ and $\mathcal{S}B_2 \subseteq \mathcal{S}B$. So by hypothesis, $\Gamma; \gamma, B_1 \vdash A$ and $\Gamma; \gamma, B_2 \vdash A$ and, by $(\vee L)$, $\Gamma; \gamma, B_1 \vee B_2 \vdash A$.
- The $B := \neg(B_1 \vee B_2)$ and $B := \neg(B_1 \wedge B_2)$ cases are similar to the cases above (respectively), and the $B := \neg\neg B_1$ case is trivial, given that $\mathcal{S}(\neg\neg B_1) = \mathcal{S}B_1$. ■

Theorem 9.5 (Completeness). *If $\Gamma \vDash A$ then $\{\{B\} \mid B \in \Gamma\} \vdash A$.*

Proof: Given our compactness theorem 5.2, we may focus on the case in which Γ is finite: let $\Gamma = \{B_1, \dots, B_n\}$. So assume $\Gamma \vDash A$. They by the characterisation theorem, for every $X \in \mathcal{S}\Gamma$, some $y \in \mathcal{S}A$ fits X . So by lemma 9.3, $X \vdash A$, for each $X \in \mathcal{S}\Gamma$. Each such X has the form $\{\{\beta_1\}, \dots, \{\beta_n\}\}$, where each $\beta_i \in \mathcal{S}B_i$. In the sequent notation, this is notated: $\beta_1; \dots; \beta_n$. And by definition of $\mathcal{S}\Gamma$, there is such a set X for each $\beta_i \in \mathcal{S}B_i$ and each $i \leq n$. So we have $\beta_1; \dots; \beta_n \vdash A$, for each $\beta_i \in \mathcal{S}B_i$, for each $i \leq n$. So by lemma 9.4 (applied n times), we have $B_1; \dots; B_n \vdash A$, which is equivalent notation for $\{\{B_1\}, \dots, \{B_n\}\} \vdash A$. ■

Theorem 9.6 (Cut-elimination). *If $\Gamma \vdash \gamma$ is derivable, then it is derivable without any instances of (CUT).*

Proof: We note that the completeness proof (9.5) does not make use of any instances of (CUT). So the system without (CUT) is sound and complete wrt \models , and hence is equivalent to the system with (CUT). ■

We are unsure of the significance of cut-elimination in this system. In general, the possibility of cut-elimination is important for proof search techniques, since (CUT) is typically the only rule in which a formula vanishes completely from upper to lower sequent (which makes proof search impossible). In the present system, however, the rule (\cdot ,2) also contains a formula in an upper sequent which may vanish in the lower sequent. So even cut-free proofs in this system may lack the subformula property. We suspect, but have no proof, that (\cdot ,2) is not eliminable from the system.

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