#### **Refuting the Halting Problem Diagonalization Argument**

Every machine that halts in a reject state is a halting computation. At least two proofs ignore this when constructing Sipser's Figure 4.5. Because these two proofs ignore this when they insert machine D into Sipser's Figure 4.5 they do so incorrectly.

When machine D is inserted into both Figure 4.4 and Figure 4.5 correctly then the contradiction goes away. Since Sipser implicitly assumes that every blank entry of Figure 4.4 is a ~halt entry Figure 4.7a makes this explicit.

	$\langle M_1 \rangle$	$\langle M_2 \rangle$	$\langle M_3 \rangle$	(M <sub>4</sub> )	(D)
$M_1$	accept	~halt	accept	~halt	reject
$M_2$	accept	accept	accept	accept	reject
Мз	~halt	~halt	~halt	~halt	accept
$M_4$	accept	accept	~halt	~halt	accept
	reject	reject	accept	accept	reject

Figure 4.7a (corrected figure 4.6, inserting D into figure 4.4)

	$\langle M_1 \rangle$	$\langle M_2 \rangle$	$\langle M_3 \rangle$	(M <sub>4</sub> )	(D)
$M_1$	<u>accept</u>	reject	accept	reject	accept
$M_2$	accept	<u>accept</u>	accept	accept	accept
Мз	reject	reject	<u>reject</u>	reject	accept
$M_4$	accept	accept	reject	<u>reject</u>	accept
	accept	accept	accept	accept	accept

**Figure 4.7b** (corrected figure 4.6, inserting D into figure 4.5)

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The following portions of pages 166-167 are directly relevant to the rebuttal. **Sipser, Michael 1997.** Introduction to the Theory of Computation. Boston: PWS Publishing Company (165-167)

Where is the diagonalization in the proof of Theorem 4.9? It becomes apparent when you examine tables of behavior for TMs H and D. In these tables we list all TMs down the rows,  $M_1, M_2, \ldots$  and all their descriptions across the columns,  $\langle M_1 \rangle, \langle M_2 \rangle, \ldots$  The entries tell whether the machine in a given row accepts the input in a given column. The entry is *accept* if the machine accepts the input but is blank if it rejects or loops on that input. We made up the entries in the following figure to illustrate the idea.

	$\langle M_1  angle$	$\langle M_2  angle$	$\langle M_3 \rangle$	$\langle M_4  angle$	
$M_1$	accept		accept		
$\overline{M_2}$	accept	accept	accept	accept	
$M_3$					
$M_4$	accept	accept			• • •
			•		
:					

### FIGURE **4.4** Entry i, j is accept if $M_i$ accepts $\langle M_i \rangle$

In the following figure the entries are the results of running H on inputs corresponding to Figure 4.4. So if  $M_3$  does not accept input  $\langle M_2 \rangle$ , the entry for row  $M_3$  and column  $\langle M_2 \rangle$  is reject because H rejects input  $\langle M_3, \langle M_2 \rangle \rangle$ .

	$\langle M_1  angle$	$\langle M_2 \rangle$	$\langle M_3  angle$	$\langle M_4  angle$	
$M_1$	accept	reject	accept	reject	
$M_2$	accept	accept	accept	accept	
$M_3$	reject	reject	reject	reject	
$M_4$	accept	accept	reject	reject	
:		;	•		

## **FIGURE 4.5** Entry i, j is the value of H on input $\langle M_i, \langle M_j \rangle \rangle$

In the following figure, we added D to Figure 4.5. By our assumption, H is a TM and so is D. Therefore it must occur on the list  $M_1, M_2, \ldots$  of all TMs. Note that D computes the opposite of the diagonal entries. The contradiction occurs at the point of the question mark where the entry must be the opposite of itself.

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	$\langle M_1  angle$	$\langle M_2  angle$	$\langle M_3  angle$	$\langle M_4 \rangle$		$\langle D  angle$	
$M_1$	accept	reject	accept	reject		accept	
$M_2$	$\overline{accept}$	accept	accept	accept		accept	
$M_3$	reject	$\overline{reject}$	reject	reject	• • •	reject	• • •
$M_4$	accept	accept	$\overline{reject}$	reject		accept	
:		:			٠		
D	reject	reject	accept	accept		- 5	
:		:					٠

# **FIGURE 4.6** If *D* is in the figure, a contradiction occurs at "?"